These measurements of the ETMX charge were done manually using awggui for excitation and diaggui for data processing. The data taken took place between UTC (2014-08-27 18:30:00) and UTC (2014-08-27 20:25:00). This is the 6th measurement after the ion pump gate valve has been opened this took place about UTC 2014-08-22 20:40:00.

I drove a sinusoidal excitation at 4Hz and amplitude 30000 counts which is equivalent to 91.5 Volts on the ESD $(30000^{*}20^{*}40/2^{18})$, as the DACs drive +-10V and they are 18 bits and then we have an amplifier of Gain 40). Notice that this actuation signal amplitude is divided to the deflection measurements in the tables below to get the standardised plots at the end of this document.

Then we monitor the deflection of the ETMX mass both in Pitch and Yaw looking at the *oplev*. The *oplev* has been carefully centred to the QPD before the measurements.

The magnitudes of the deflection given below are in *urad* and are obtained through a power spectrum plot of the oplev pitch and yaw signals. This power spectrum was measured with a **BW** = 0.02Hz (actual value is 0.0234375) on the range between 1 - 5 Hz and averaged **3** times.

During the measurements the coherence between excitation and Pitch and Yaw was monitored to be sure that the excitation was observed. I also measured the phase (in degrees) of the transfer function between excitation and oplev pitch and yaw (the phase was measured to confirm it is 180 degrees different for the deflections with + and - BIAS). The same excitation was applied to the 4 quadrants of the ESD.

The ETMX pressure at PT-510 is 2.7e-7 good enough for these measurements. ISI Watchdog ST1 and ST2 green so no much drift of the oplev. Next I show the results:

V BIAS (Volts)	Pit	ch	Yaw		
	Mag (urad)	Phase (deg)	Mag (urad)	Phase (deg)	
+390.5	4.9102e-3	177	5.1093e-3	2	
+195.3	1.8468e-3	176	2.1334e-3	5	
-195.3	3.343e-3	-2	3.5503e-3	179	
-390.5	5.7287e-3	-1	6.5001e-3	180	

Driving UR quadrant: low coherence +195V in yaw

Driving UL quadrant:

	Pit	ch	Yaw		
V BIAS (VOILS)	Mag (urad)	Phase (deg)	Mag (urad)	Phase (deg)	
+390.5	4.2475e-3	179	5.151e-3	178	
+195.3	1.7832e-3	177	2.0266e-3 (low coherence 0.96)	178	
-195.3	3.574e-3	5	3.9358e-3	3	
-390.5	6.0556e-3	0	7.0e-3	-4	

Driving LL quadrant: low coherence +195V in yaw

	Pit	tch	Yaw		
V BIAS (VOILS)	Mag (urad)	Phase (deg)	Mag (urad)	Phase (deg)	
+390.5	4.4457e-3	-3	5.0977e-3	180	
+195.3	2.7137e-3		2.4117e-3	174	
		0	(low		
			coherence		
			0.97)		
-195.3	1.6219e-3	177	3.7197e-3	0	
-390.5	3.5917e-3	180	6.5793e-3	2	

Driving LR quadrant: low coherence +195V

	Pit	tch	Yaw		
V BIAS (VOILS)	Mag (urad)	Phase (deg)	Mag (urad)	Phase (deg)	
+390.5	3.8119e-3	-1			
+195.3	1.5e-3	0	1.6913e-3 (low coherence 0.93)	13	
-195.3	2.689e-3	-179	4.294e-3	177	
-390.5	4.7986e-3	180	6.791e-3	175	

Plotting the above results in the standard way "Normalised deflection [μ rad/V] vs V BIAS", the normalisation of the deflection is by the amplitude of the excitation = 91.5Volt. Comparison between measurement 21, 22 and current (measurement 26):



	UL - 21	UL - 22	UL - 26	UR - 21	UR – 22	UR - 26	LR - 21	LR - 22	LR - 26	LL - 21	LL - 22	LL - 26
Veff PITCH [V]	53	34	68	37.5	29	43	62	116	50	66	87	-47
PITCH slope [10 ⁻⁷ μrad/ V]	-1.478	-1.4889	-1.452	-1.4403	-1.4715	-1.4802	1.1073	1.0992	1.1973	1.2048	1.1582	1.1414
Veff YAW [V]	47	34	61	39	34	47	67	98	87	42	104	46
YAW slope [10 ⁻⁷ µrad/ V]	-1.7636	-1.7234	-1.6925	1.5308	1.5451	1.6163	1.5125	1.5742	1.5799	- 1.6396	- 1.6419	-1.6489