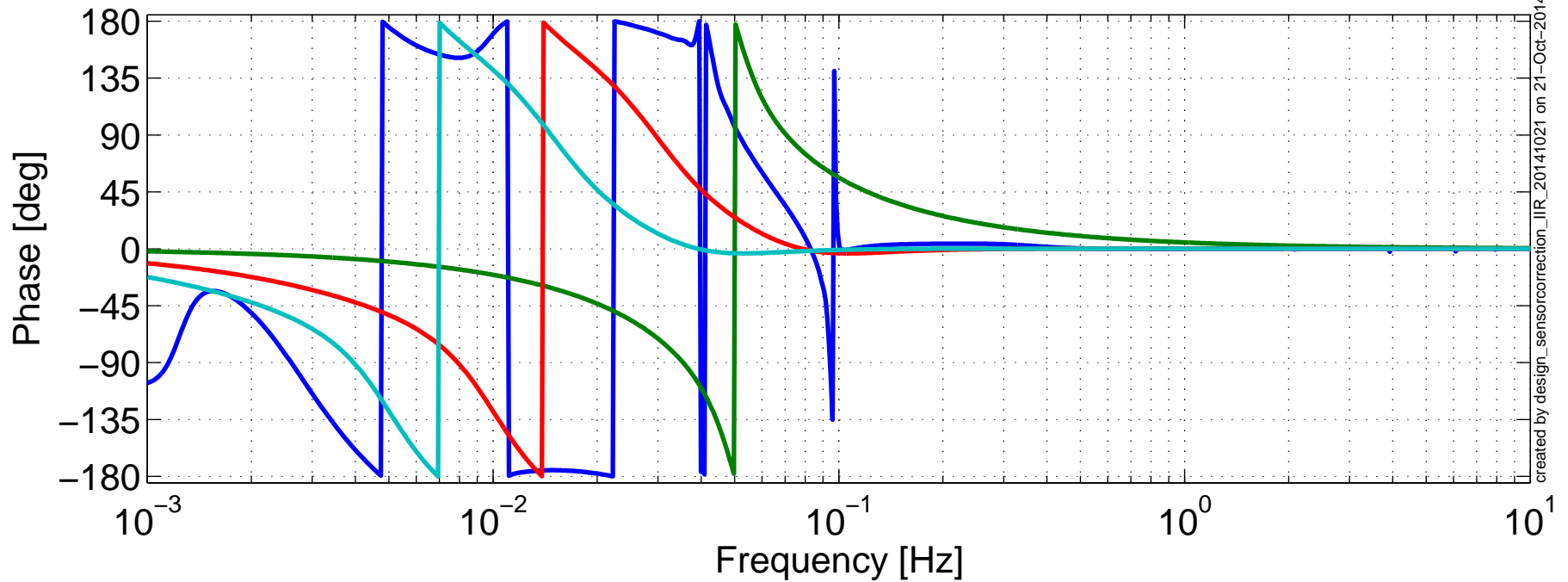
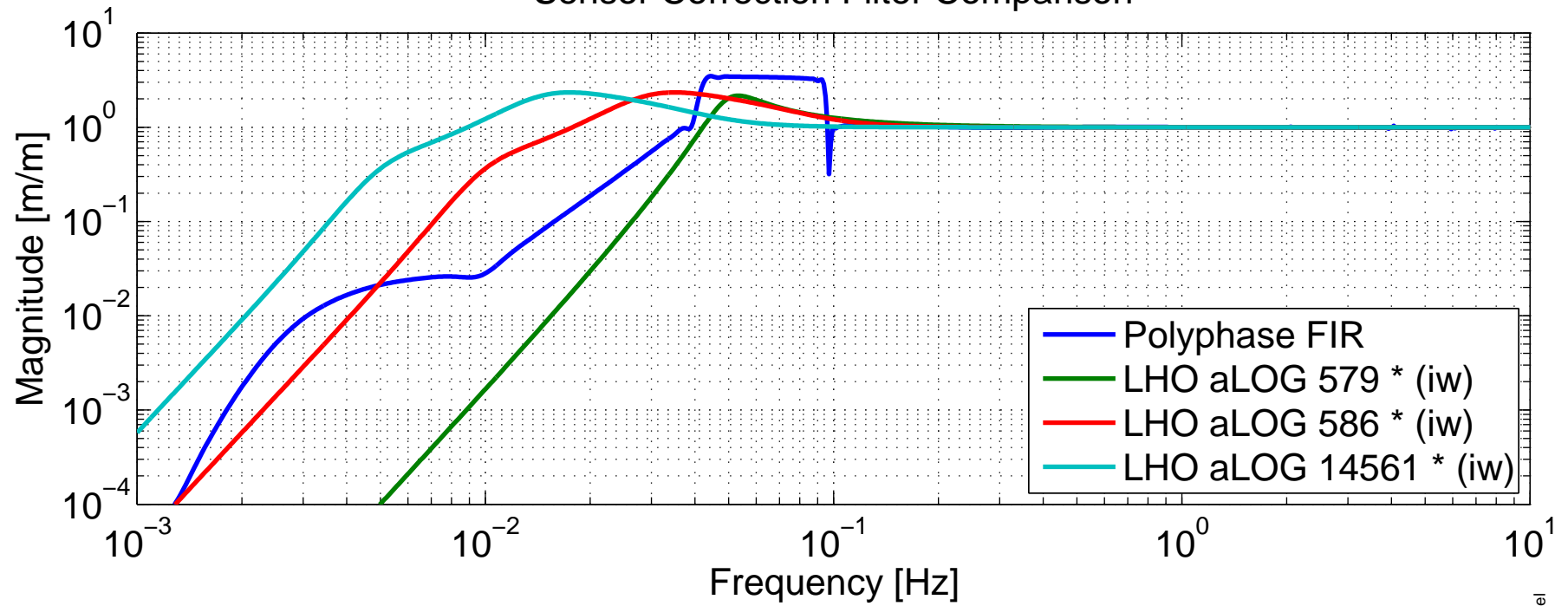
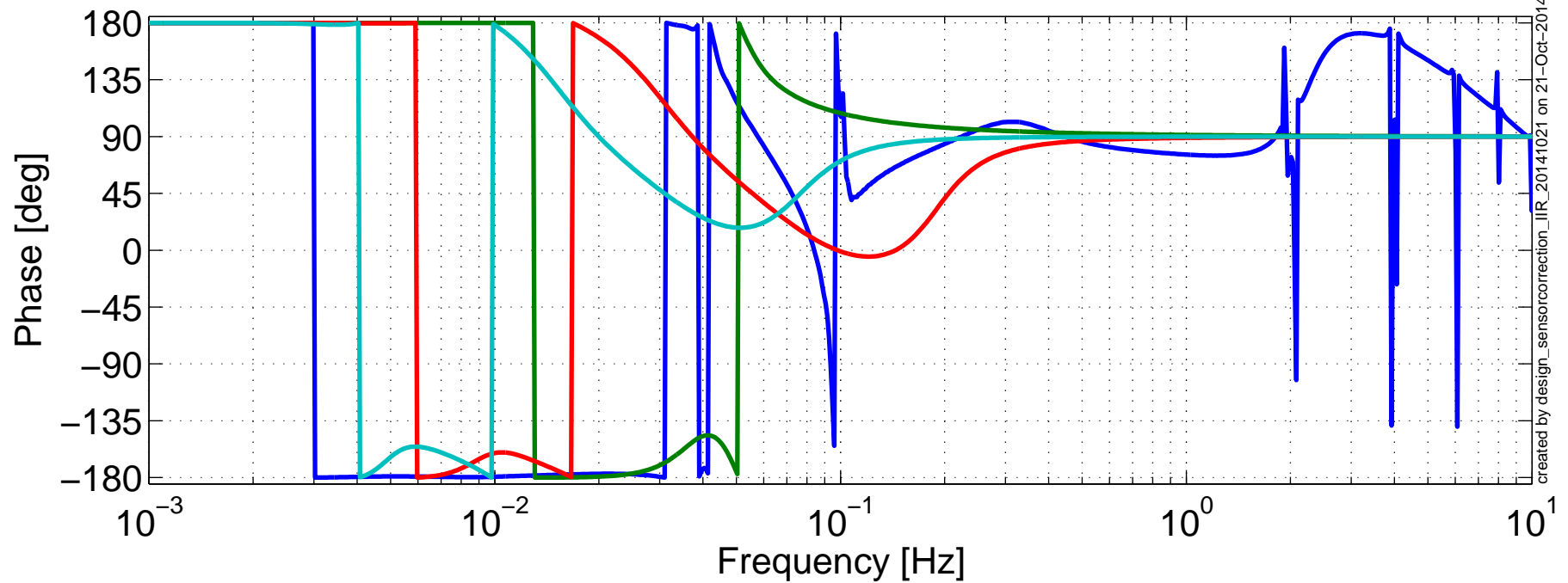
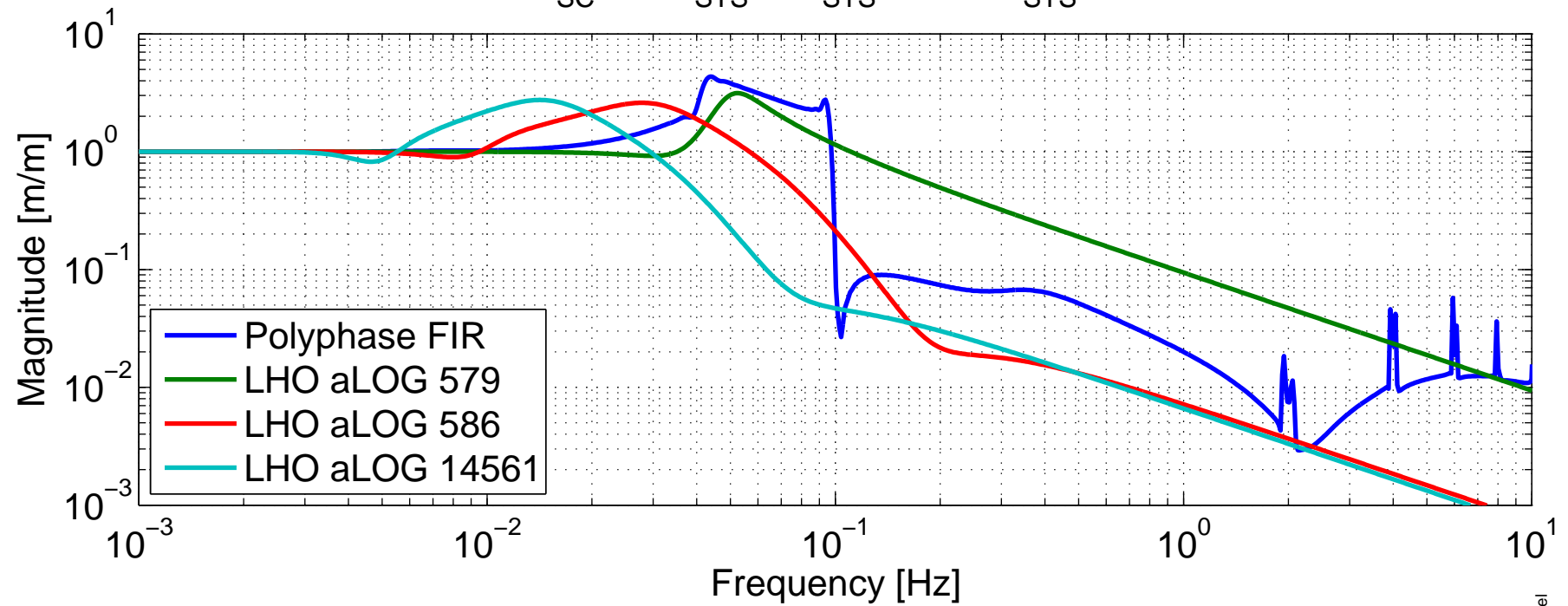


# Sensor Correction Filter Comparison

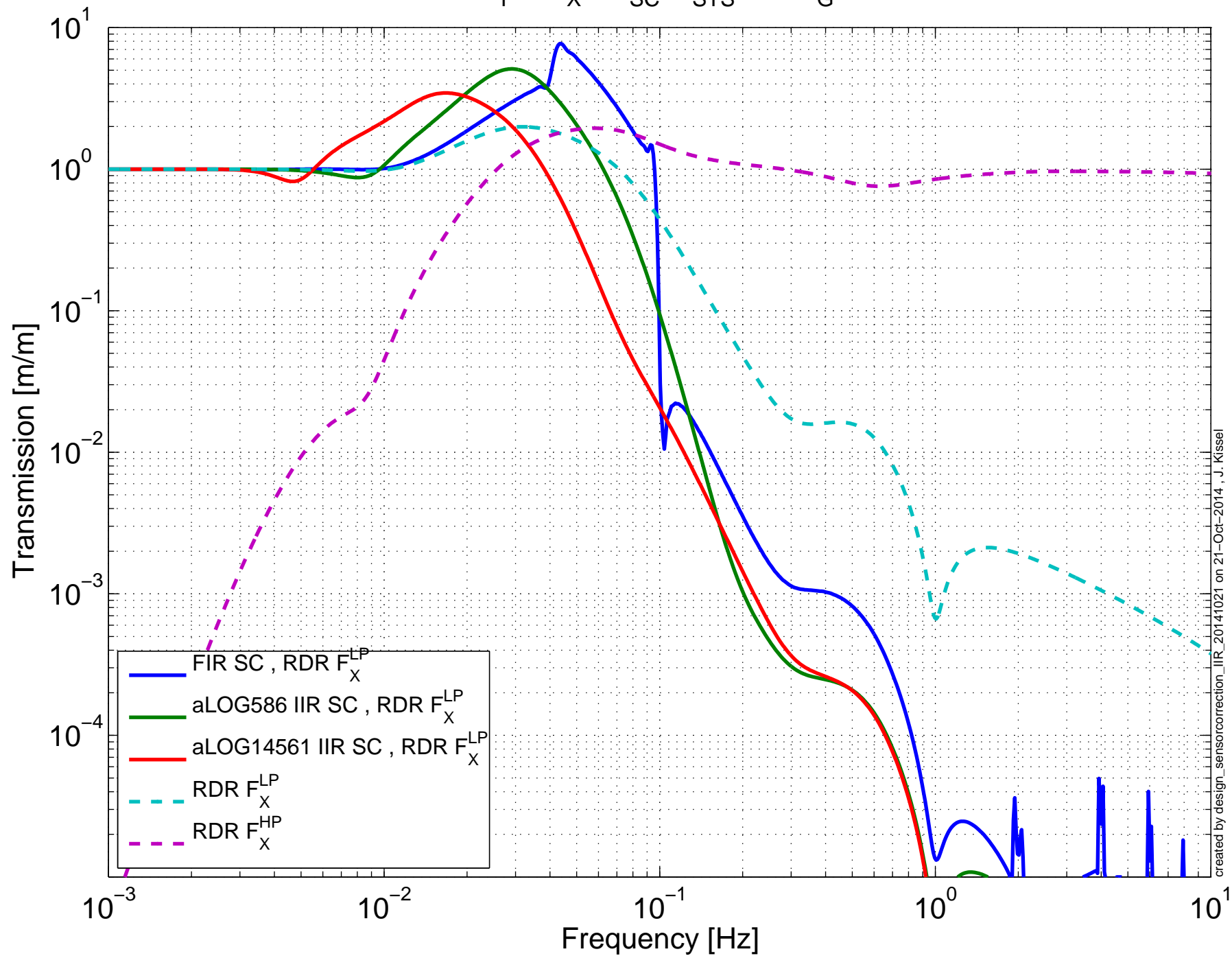


$$(F_{SC} - 1/R_{STS}) * R_{STS} = (SC * R_{STS} - 1)$$

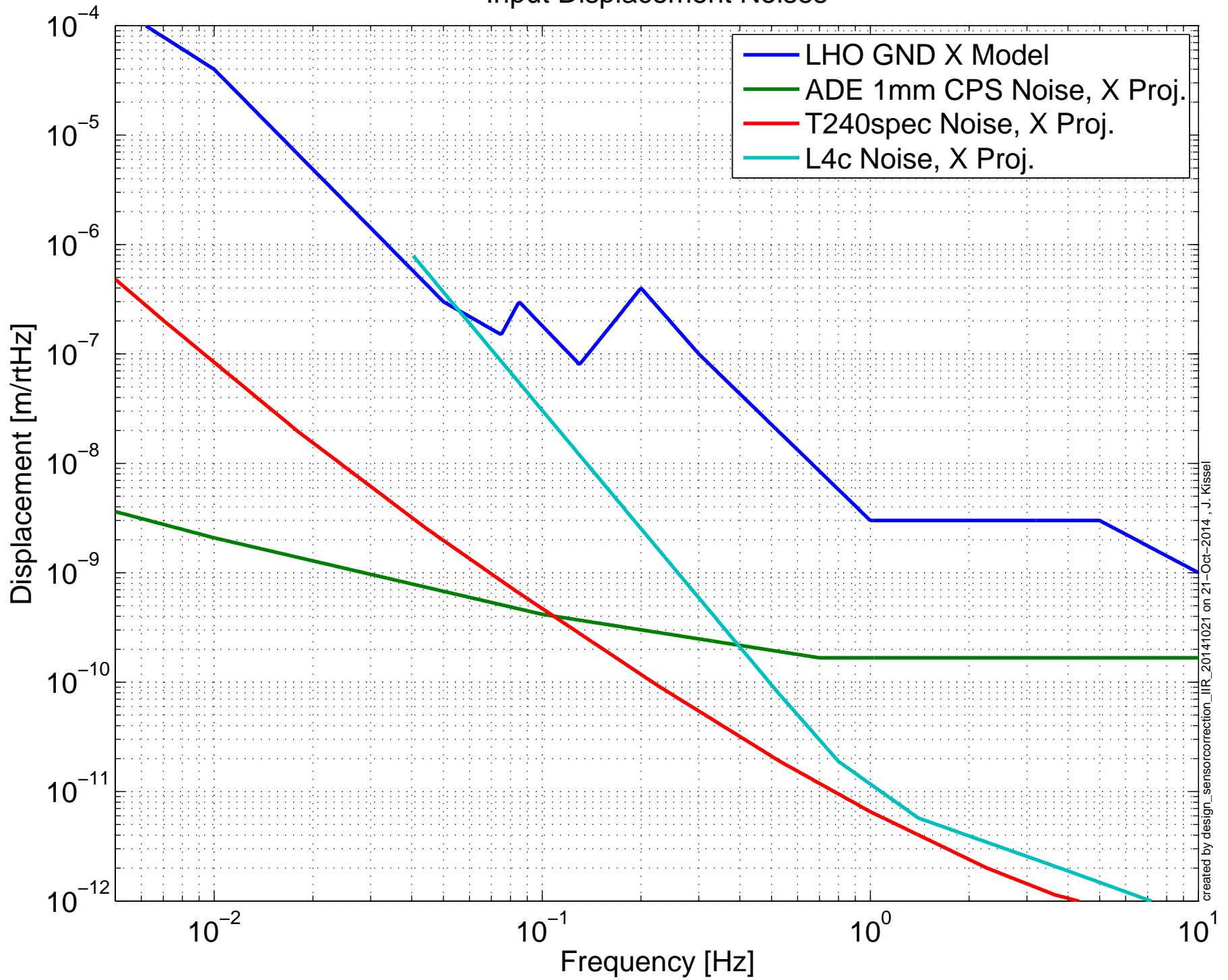


# Transmission Model, RDR Blends, SC Comparison

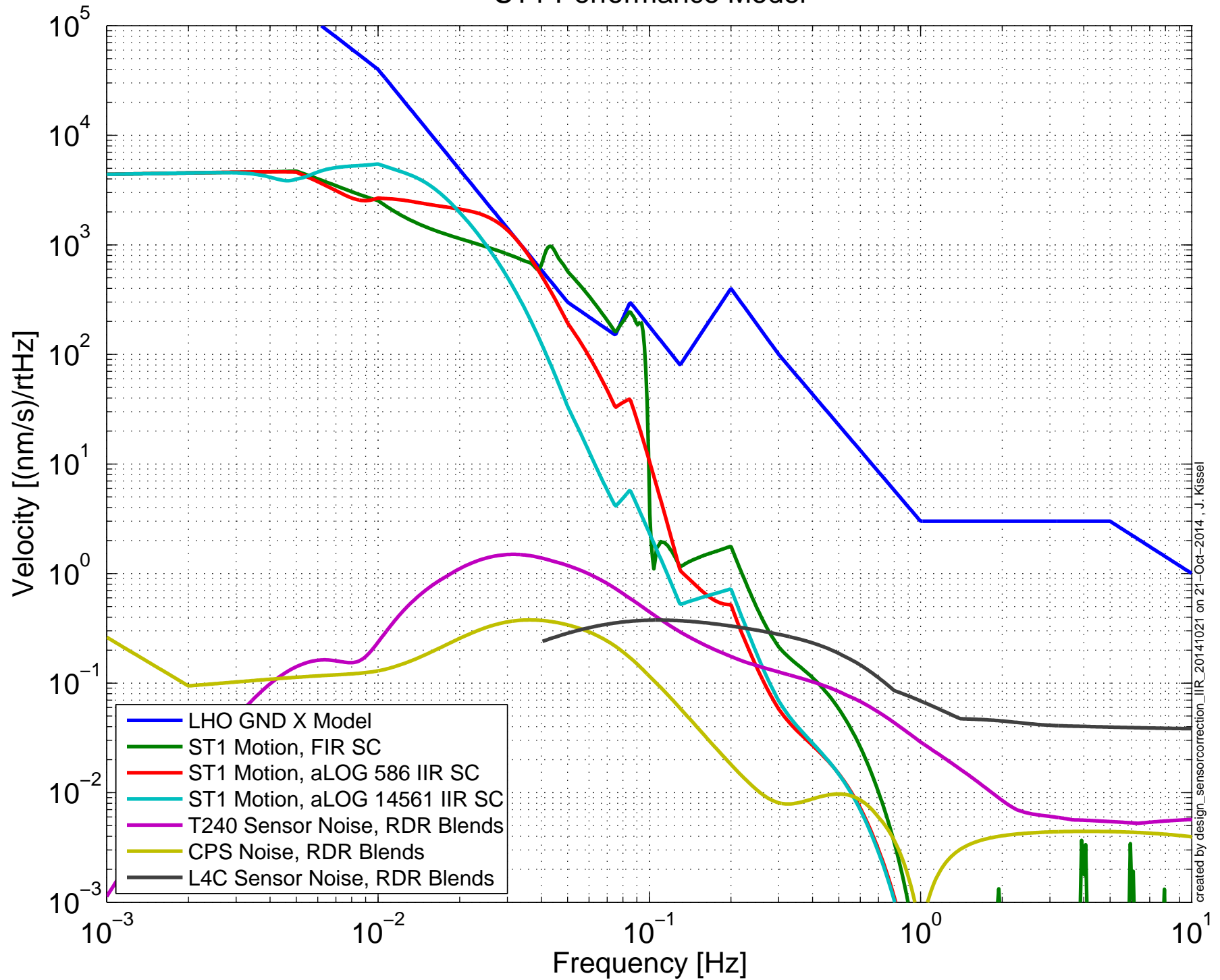
$$x_P = F_X^{LP} (F_{SC} * R_{STS} - 1) x_G$$



# Input Displacement Noises

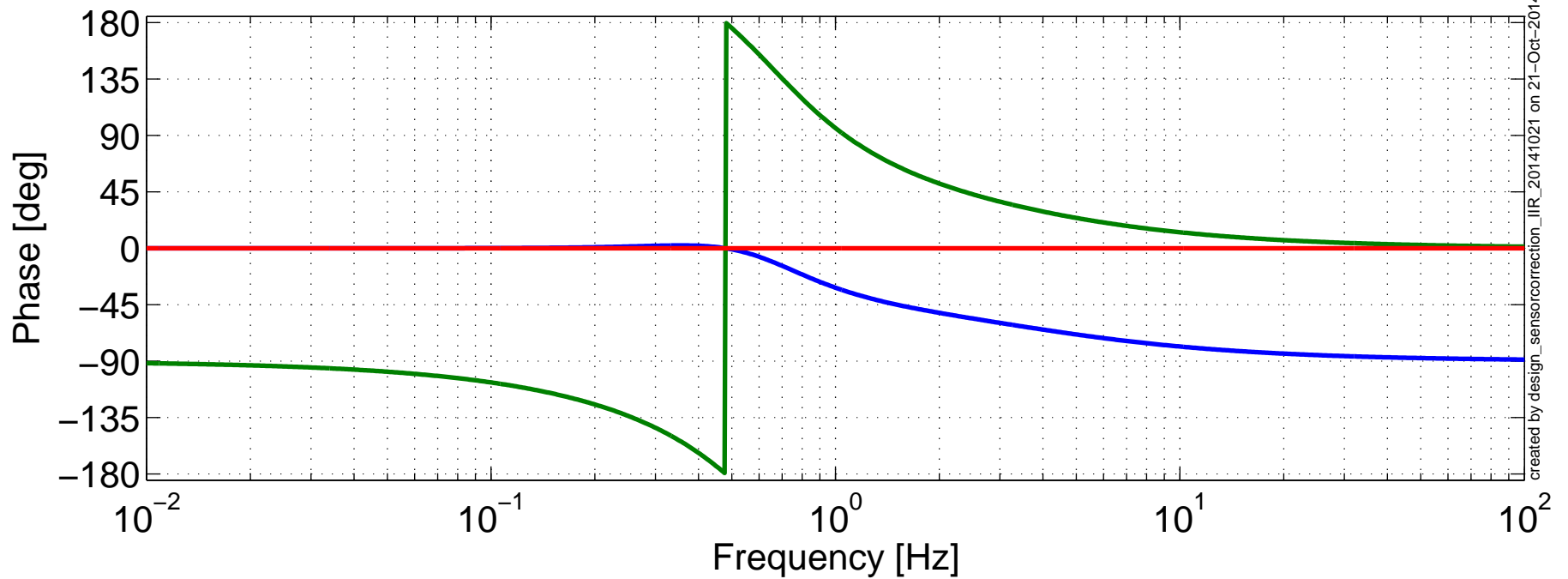
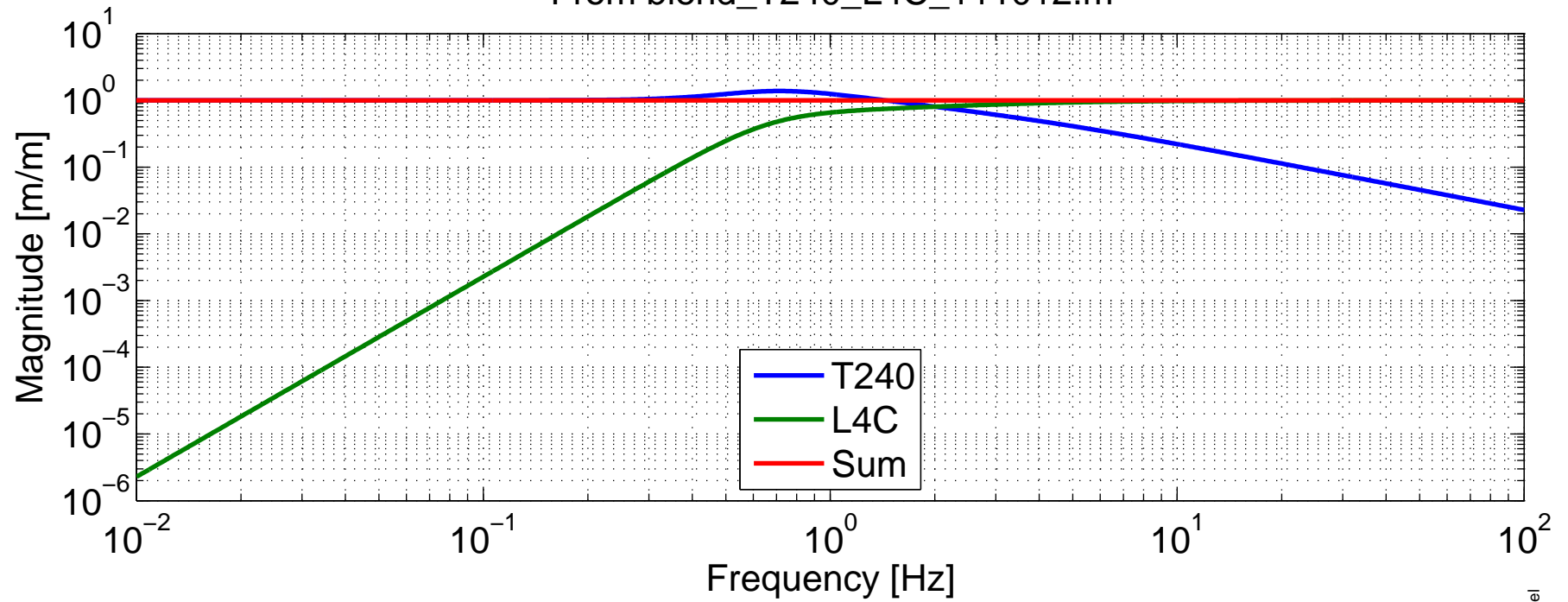


# ST1 Performance Model

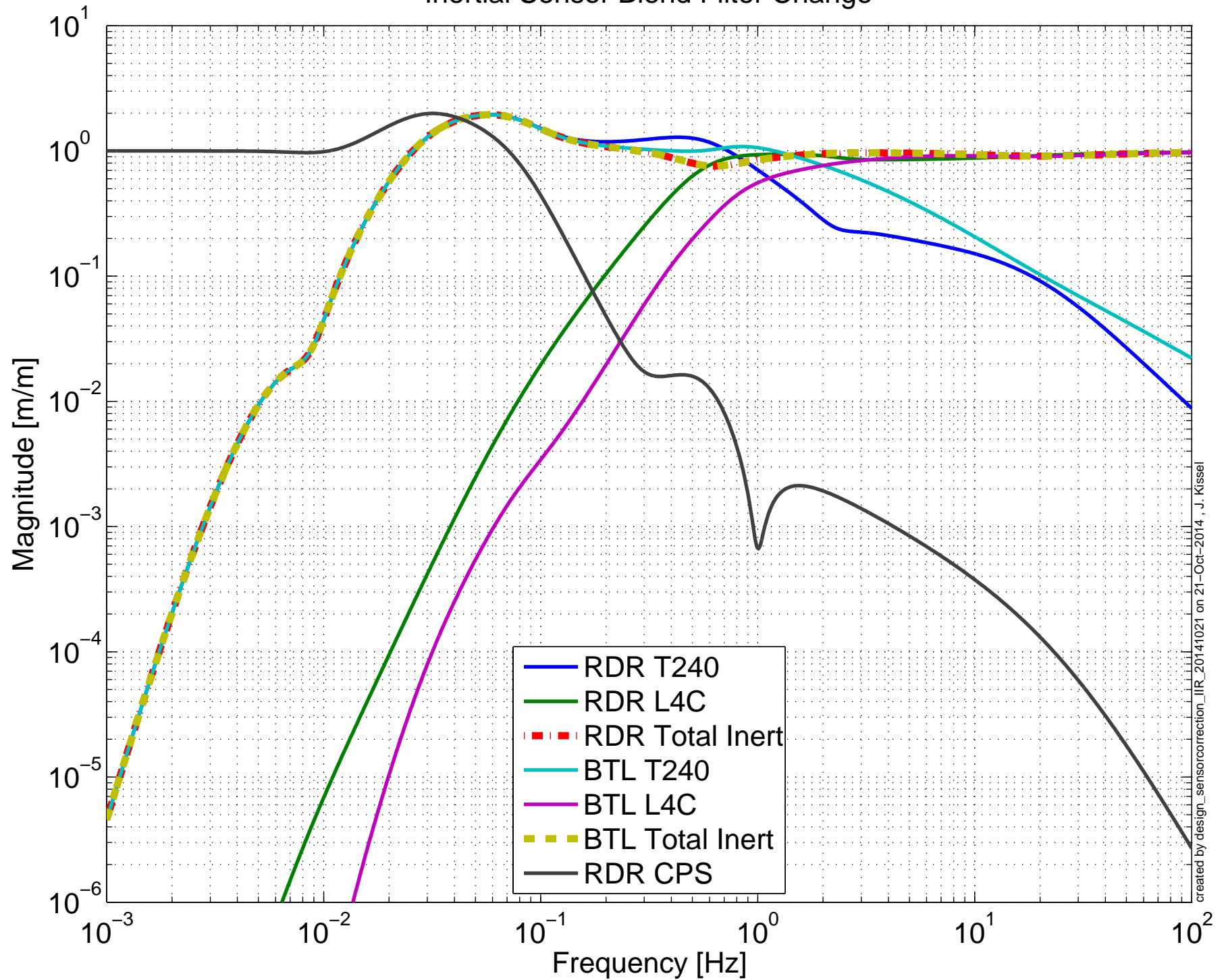


# BTL ST1 Inertial Sensor Blends

From blend\_T240\_L4C\_111012.m



# Inertial Sensor Blend Filter Change



# ST1 Performance Model

