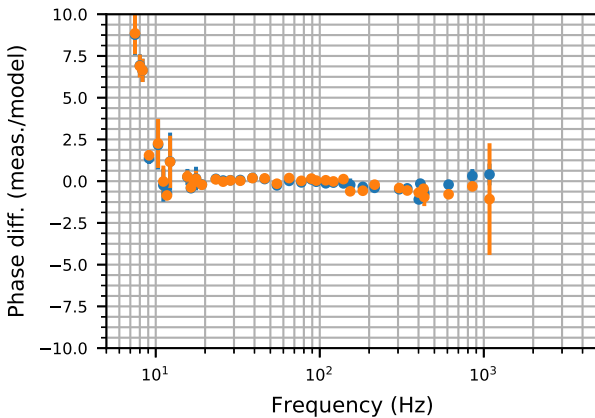
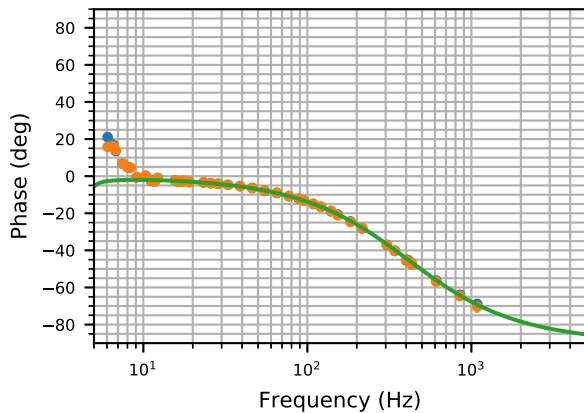
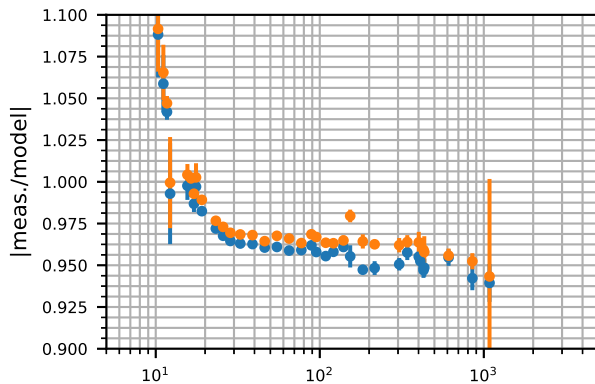
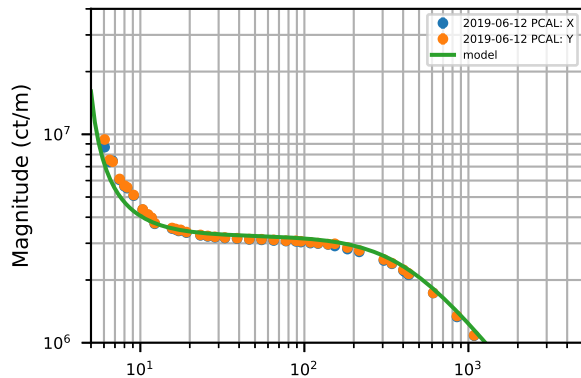
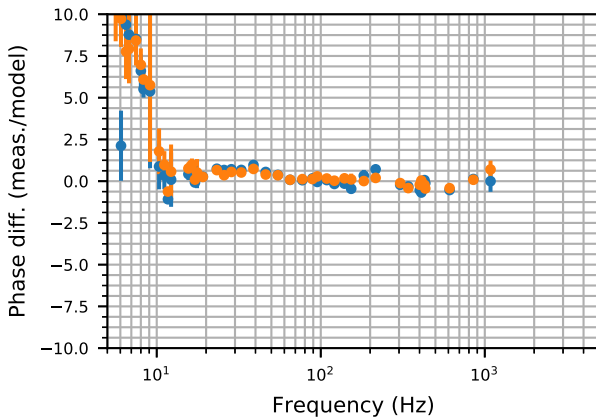
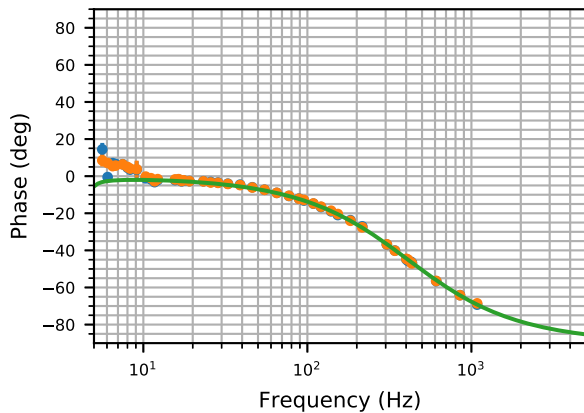
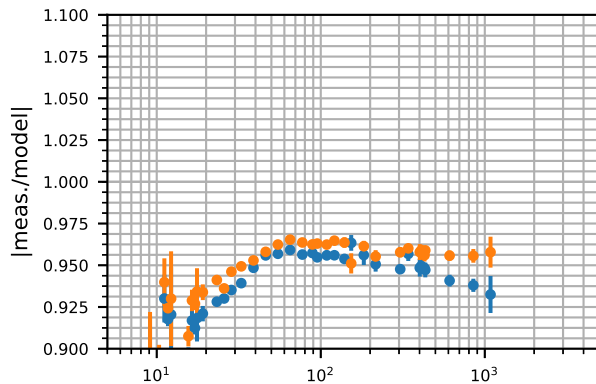
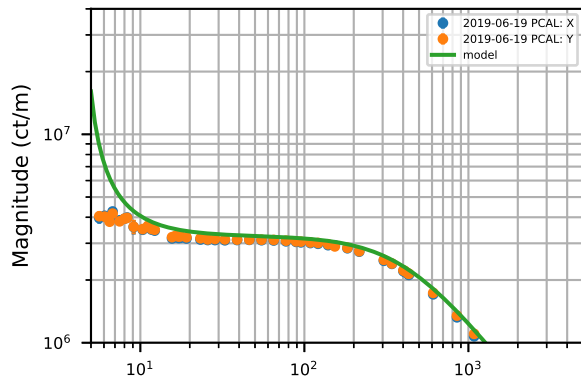


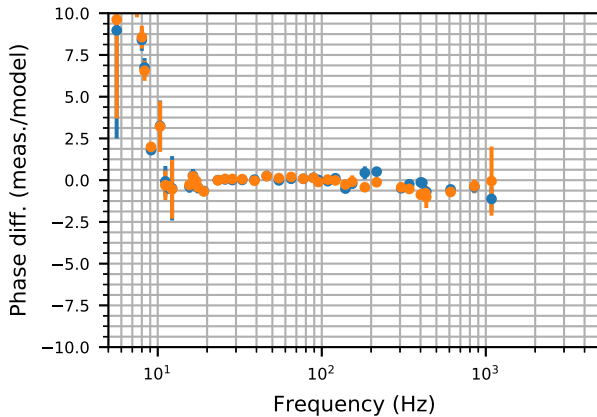
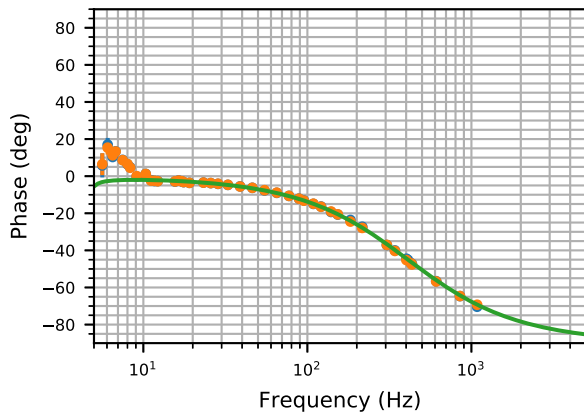
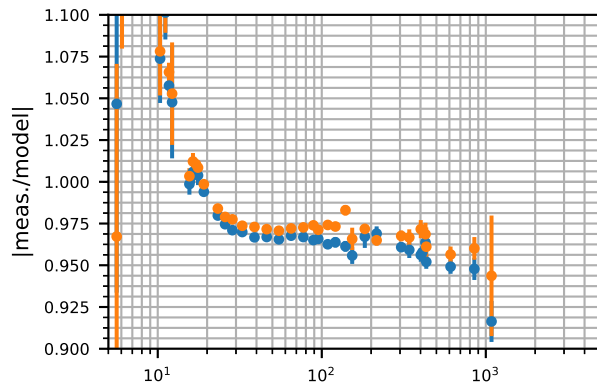
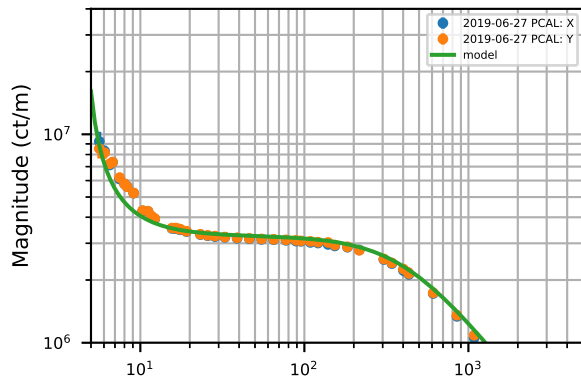
H1 Reference Sensing Model Used: $H_C = 3.25\text{e}+06$ ct/m, $f_{cc} = 4.11\text{e}+02$ Hz, $f_s = 4.47$ Hz, $Q=52.1$



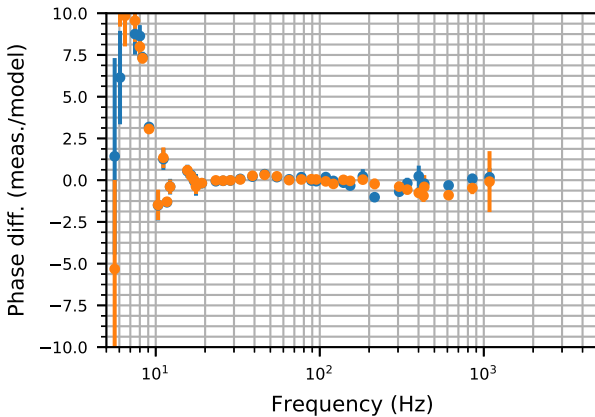
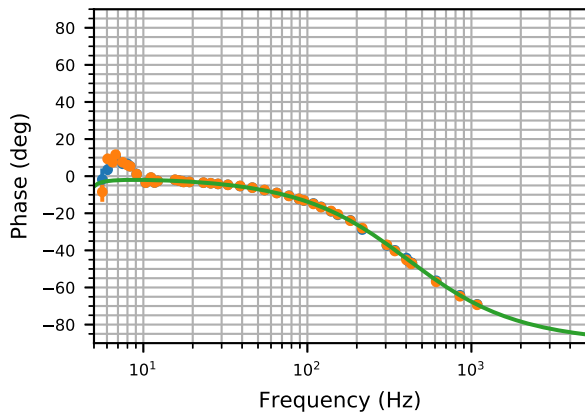
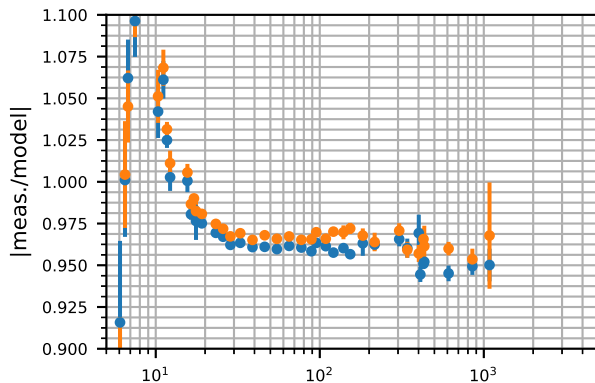
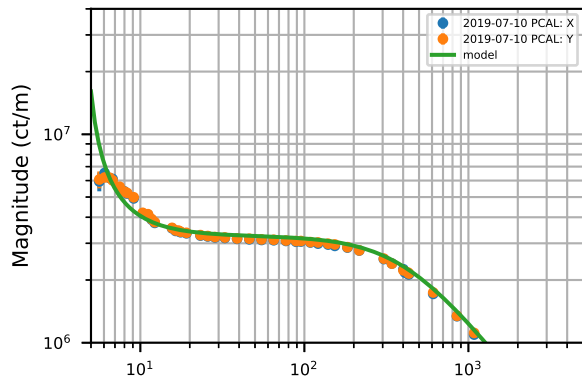
H1 Reference Sensing Model Used: $H_C = 3.25\text{e}+06$ ct/m, $f_{cc} = 4.11\text{e}+02$ Hz, $f_s = 4.47\text{j}$ Hz, $Q=52.1$



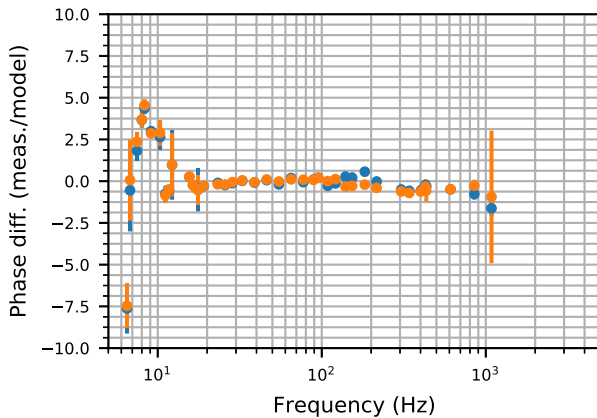
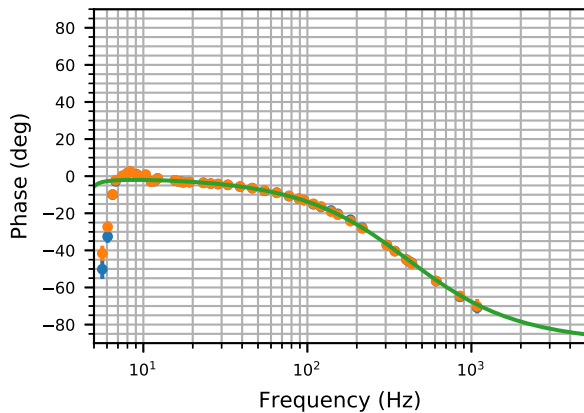
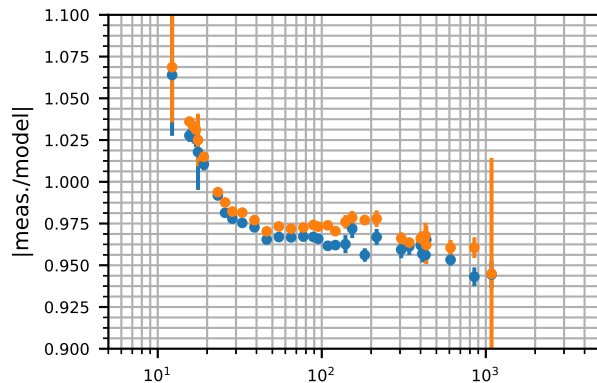
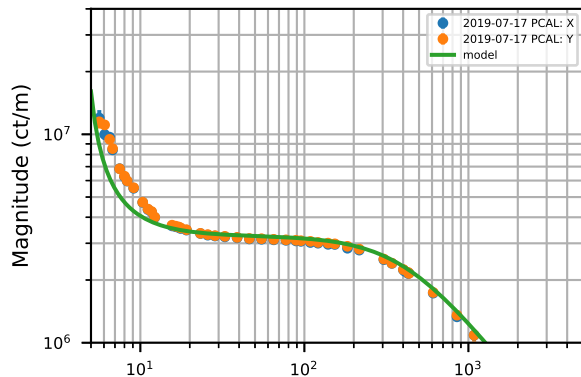
H1 Reference Sensing Model Used: $H_C = 3.25\text{e}+06$ ct/m, $f_{cc} = 4.11\text{e}+02$ Hz, $f_s = 4.47$ Hz, $Q=52.1$



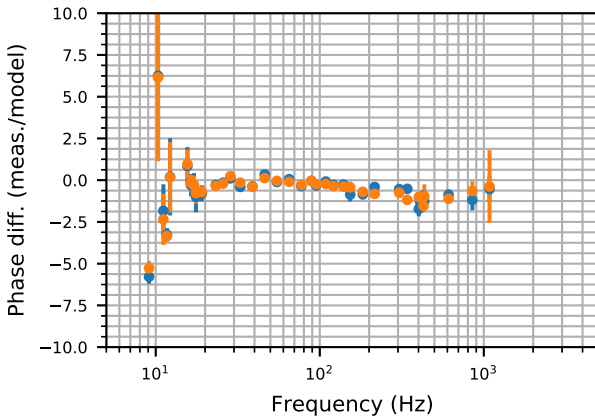
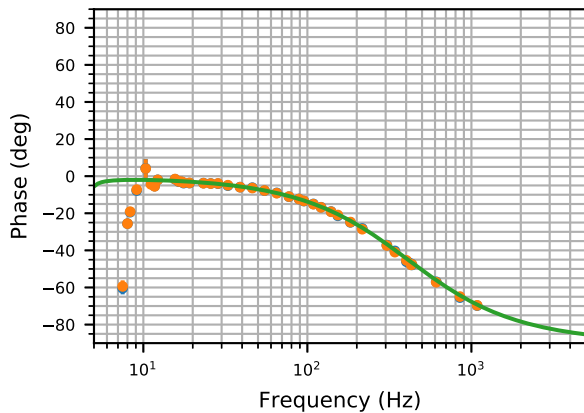
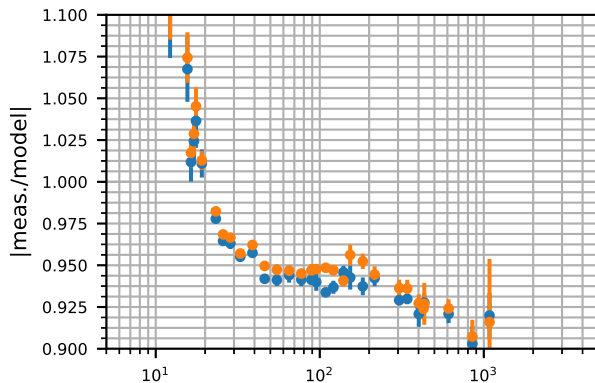
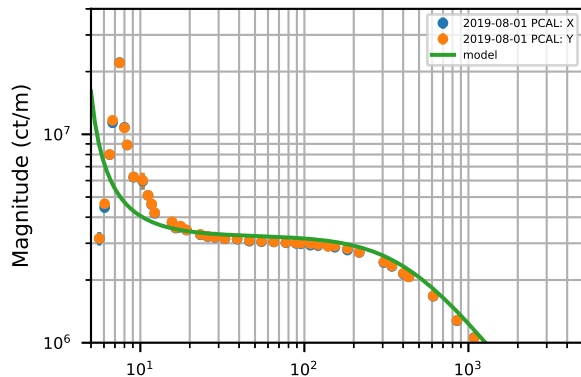
H1 Reference Sensing Model Used: $H_C = 3.25\text{e}+06$ ct/m, $f_{cc} = 4.11\text{e}+02$ Hz, $f_s = 4.47$ Hz, $Q=52.1$



H1 Reference Sensing Model Used: $H_C = 3.25\text{e}+06$ ct/m, $f_{cc} = 4.11\text{e}+02$ Hz, $f_s = 4.47$ Hz, $Q=52.1$

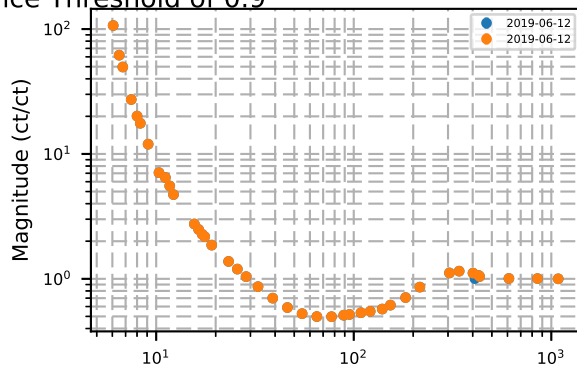
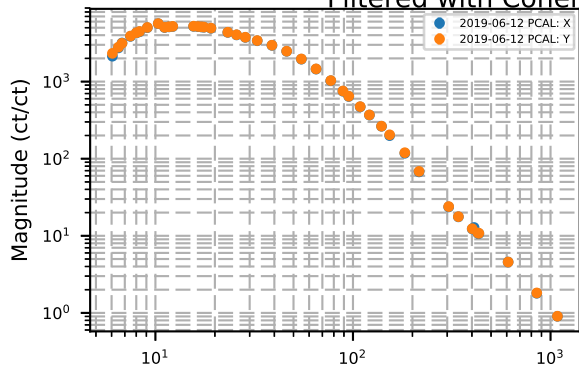


H1 Reference Sensing Model Used: $H_C = 3.25\text{e}+06$ ct/m, $f_{cc} = 4.11\text{e}+02$ Hz, $f_s = 4.47$ Hz, $Q=52.1$

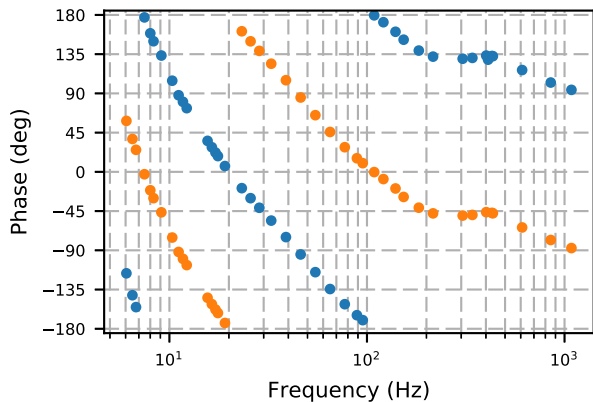


2019-06-12 H1 Sensing Function: Raw Imported Data

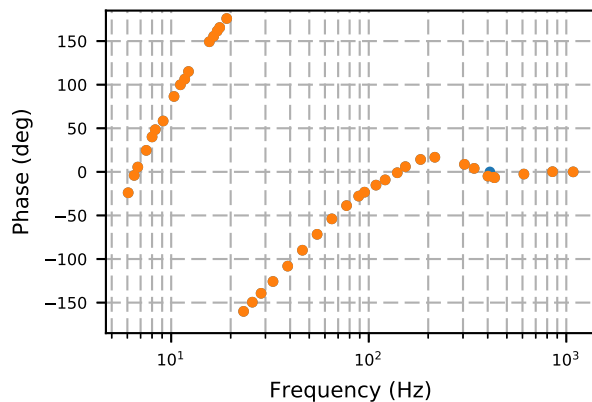
Filtered with Coherence Threshold of 0.9



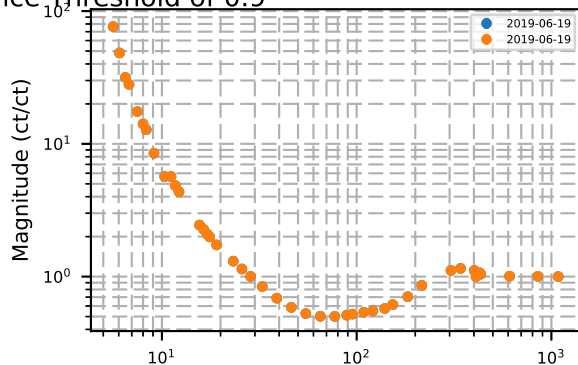
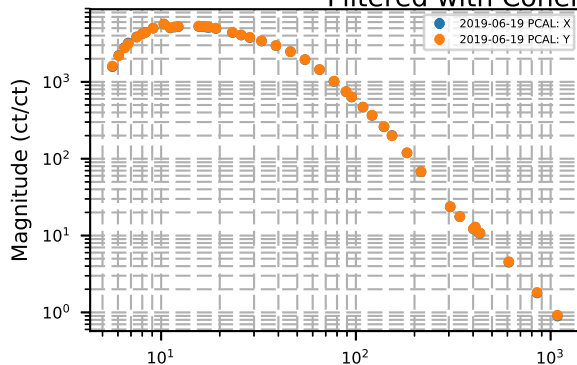
$$\hat{\text{DARM IN1}} / \text{PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$



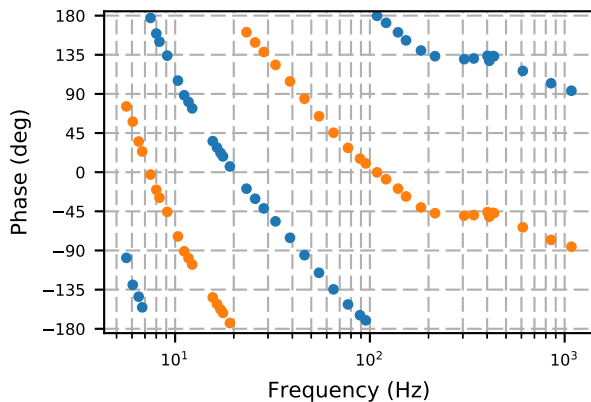
$$\hat{\text{DARM EXC}} / \text{DARM IN2} = (1 + C A D) v$$



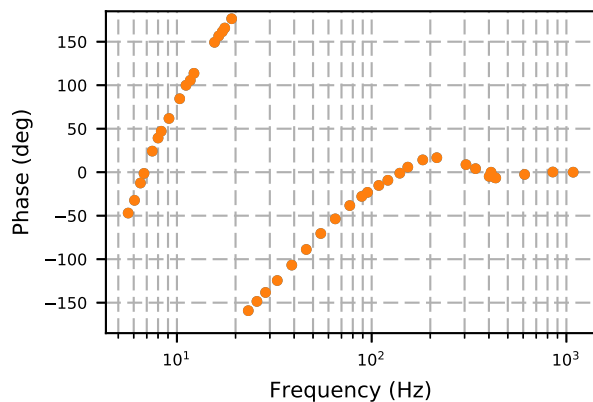
2019-06-19 H1 Sensing Function: Raw Imported Data Filtered with Coherence Threshold of 0.9



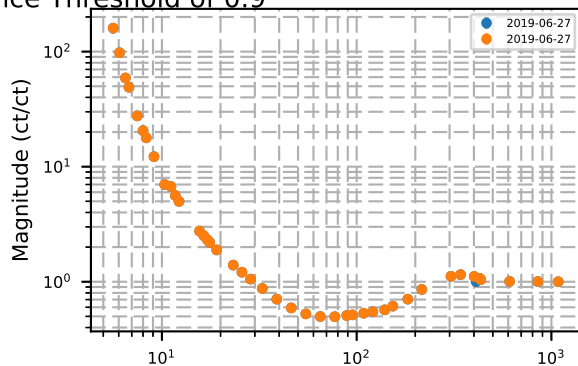
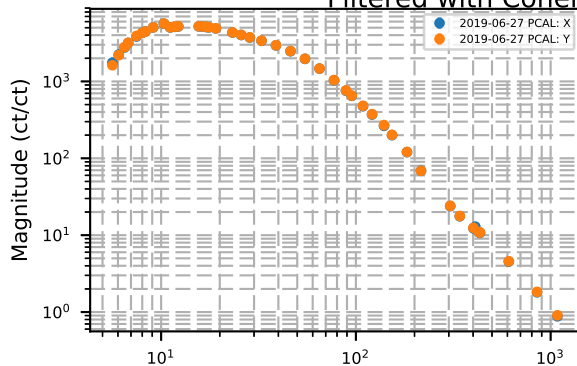
$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$



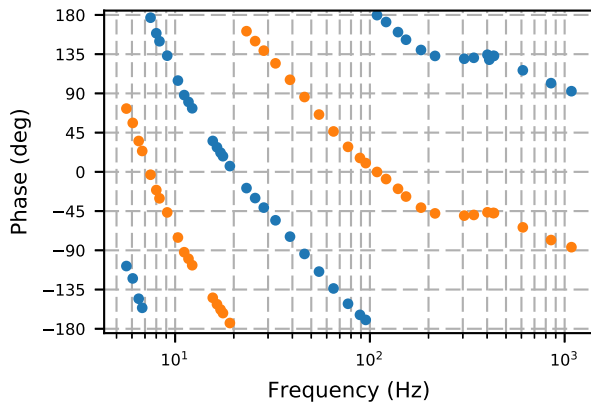
$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$



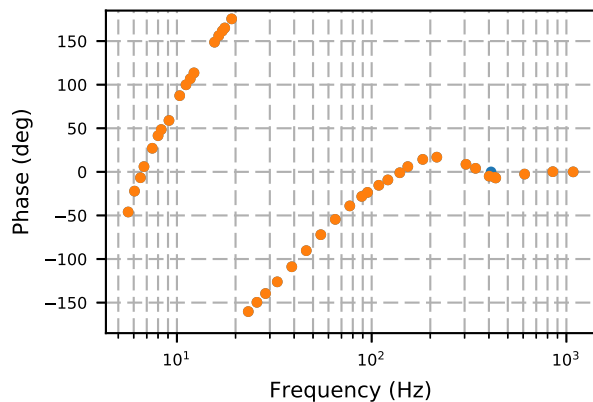
2019-06-27 H1 Sensing Function: Raw Imported Data Filtered with Coherence Threshold of 0.9



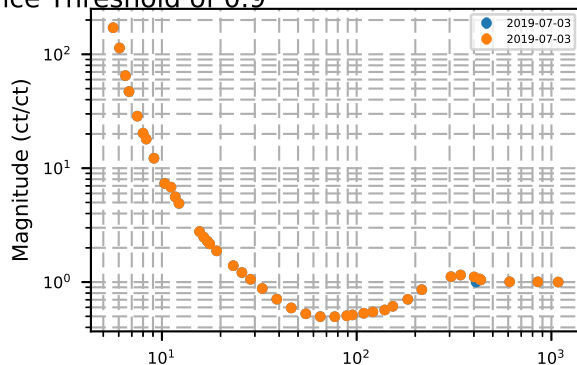
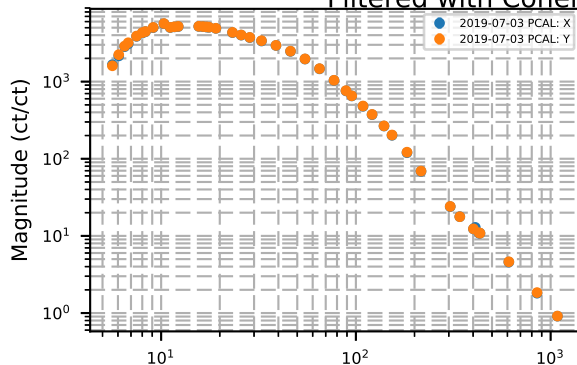
$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$



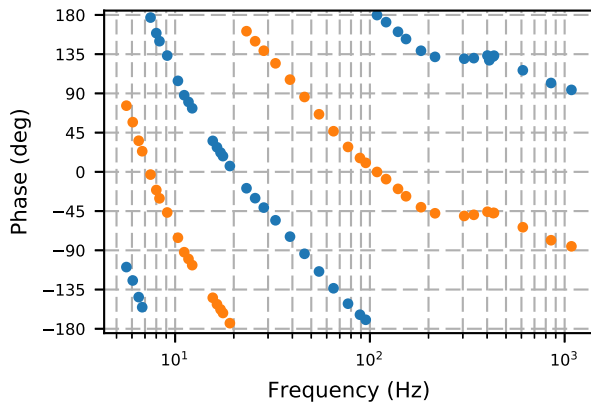
$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$



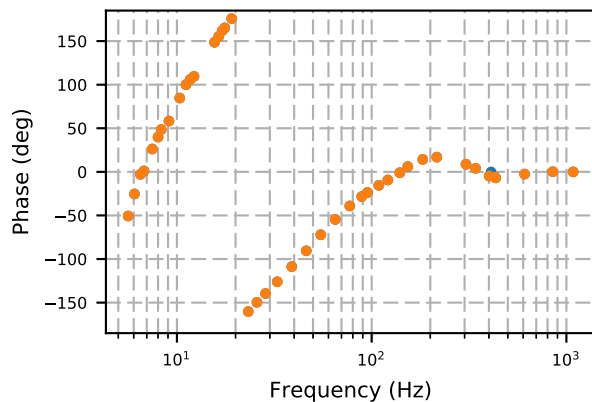
2019-07-03 H1 Sensing Function: Raw Imported Data Filtered with Coherence Threshold of 0.9



$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$

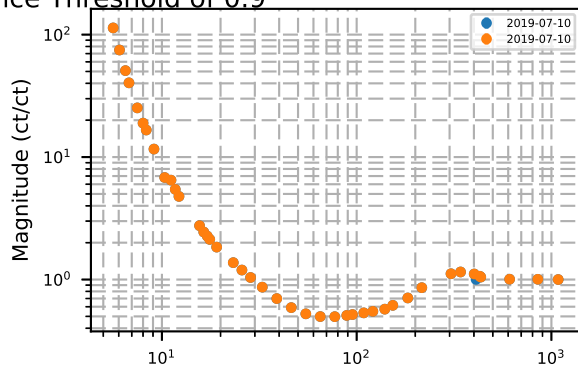
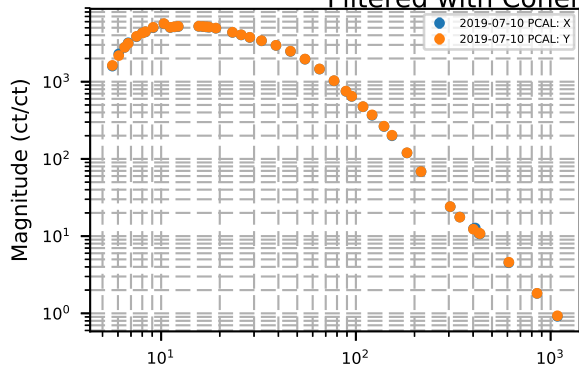


$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$

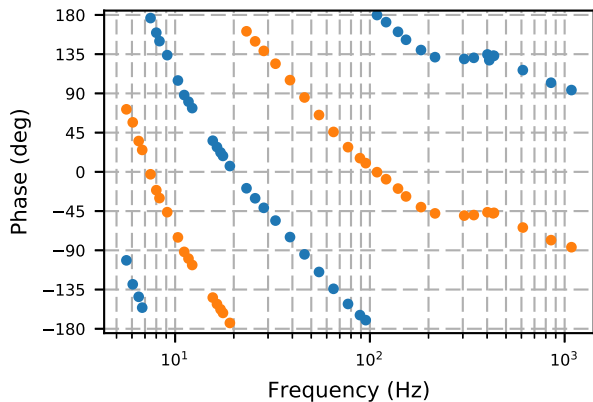


2019-07-10 H1 Sensing Function: Raw Imported Data

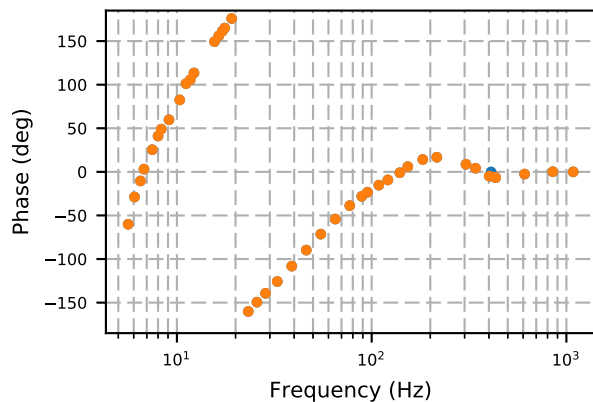
Filtered with Coherence Threshold of 0.9



$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$

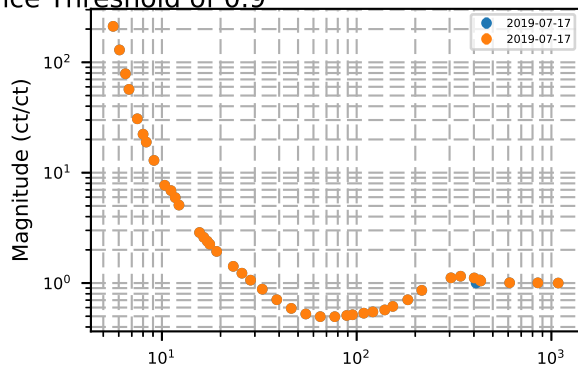
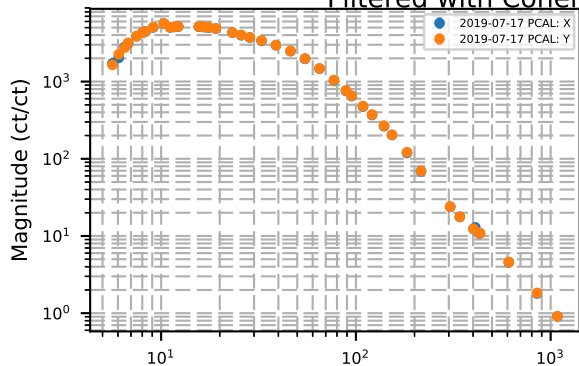


$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$

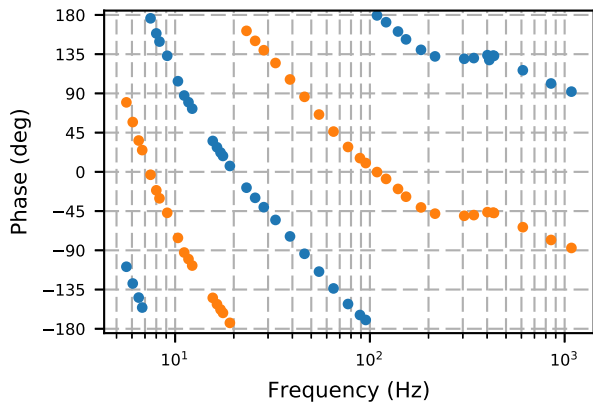


2019-07-17 H1 Sensing Function: Raw Imported Data

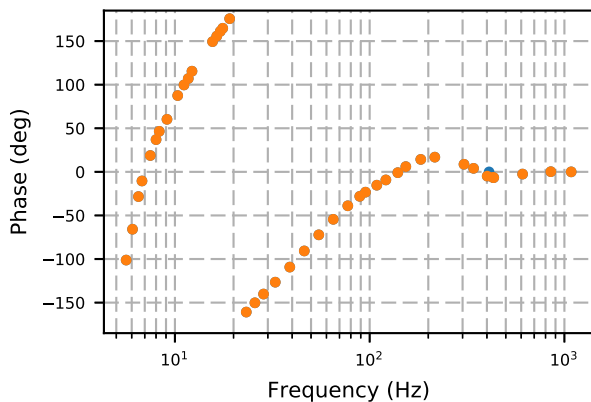
Filtered with Coherence Threshold of 0.9



$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$

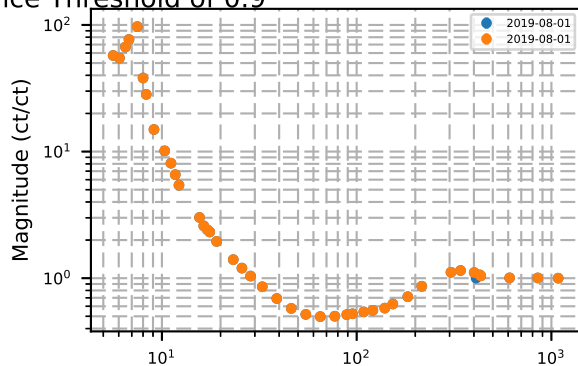
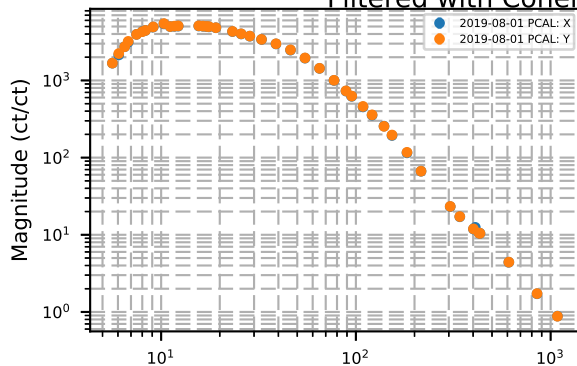


$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$

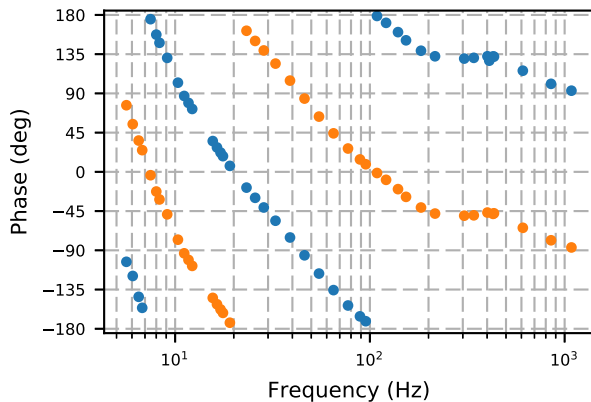


2019-08-01 H1 Sensing Function: Raw Imported Data

Filtered with Coherence Threshold of 0.9



$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$



$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$

