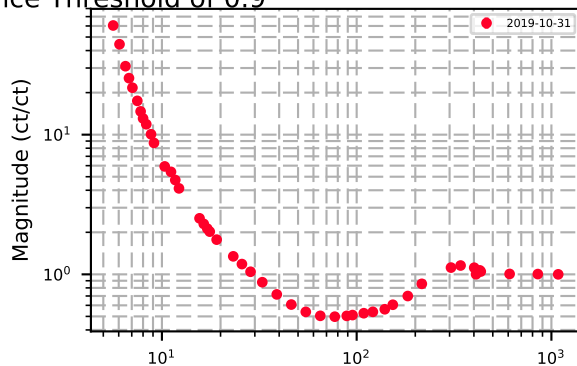
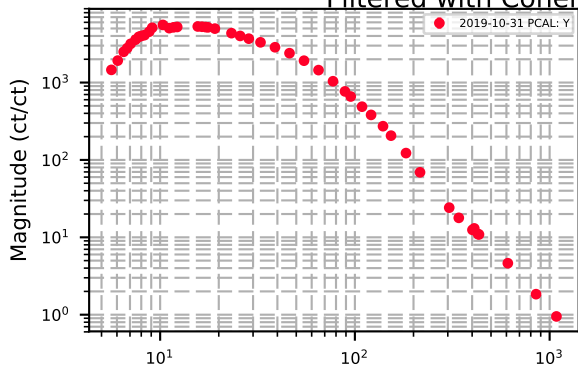
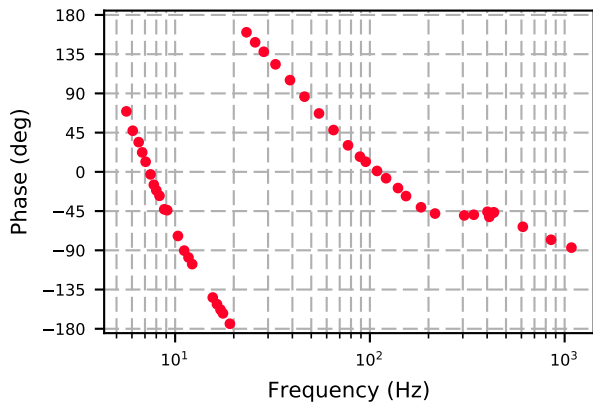


2019-10-31 H1 Sensing Function: Raw Imported Data Filtered with Coherence Threshold of 0.9



$$\wedge \text{ DARM IN1 / PCALY} = \text{pcalFlaws} * C / (1 + C A D) v$$



$$\wedge \text{ DARM EXC / DARM IN2} = (1 + C A D) v$$

