

<u>Time from Offsets Set</u>	<u>GPS Time</u>	<u>State Explanation</u>	<u>State Number</u>	<u>Pitch Offset</u>	<u>Yaw Offset</u>
	1264375812	<u>initial alignment</u>	7	0	0
0	1264377370	<u>ISC_LOCK = 110</u>	110	1078	368
421	1264377791	<u>Offsets set to Zero</u>	435	0	0
90	1264377881	<u>Lockloss</u>	9	0	0
0	1264378417	<u>ISC_LOCK = 110</u>	110	1115	519
402	1264378819	<u>Offsets set to Zero</u>	435	0	0
216	1264379035	<u>Lockloss</u>	9	0	0
0	1264379668	<u>ISC_LOCK = 110</u>	110	1352	565
438	1264380106	<u>Offsets set to Zero</u>	430	0	0
237	1264380343	<u>Lockloss</u>	9	0	0
0	1264380843	<u>ISC_LOCK = 110</u>	110	1545	649
409	1264381252	<u>Offsets set to Zero</u>	435	0	0
188	1264381440	<u>Lockloss</u>	9	0	0
0	1264381911	<u>ISC_LOCK = 110</u>	110	1753	613
409	1264382320	<u>Offsets set to Zero</u>	430	0	0
384	1264382704	<u>Lockloss</u>	9	0	0
0	1264383194	<u>ISC_LOCK = 110</u>	110	1425	523
412	1264383606	<u>Offsets set to Zero</u>	430	0	0
2126	1264385732	<u>Lockloss</u>	9	0	0
	1264387308	<u>initial alignment</u>	7	0	0
0	1264389469	<u>ISC_LOCK = 110</u>	110	623	701
409	1264389878	<u>Offsets set to Zero</u>	435	0	0
81	1264389959	<u>Lockloss</u>	10	0	0
0	1264439632	<u>ISC_LOCK = 110</u>	110	547	456
615	1264440247	<u>Offsets set to Zero</u>	435	0	0
88	1264440335	<u>Lockloss</u>	9	0	0
0	1264889081	<u>ISC_LOCK = 110</u>	110	1366	-173
603	1264889684	<u>Offsets set to Zero</u>	435	0	0
1413	1264891097	<u>Lockloss</u>	9	0	0

Average Pitch Offset		1200
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Average Yaw Offset			469
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