

<u>Time from Offsets Set</u>	<u>GPS Time</u>	<u>State Explanation</u>	<u>State Number</u>	<u>Pitch Offset</u>	<u>Yaw Offset</u>
	1264334020	<u>H1 reaches NLN</u>	600	0	0
0	1264391053	<u>ISC_LOCK = 110</u>	110	830	473
635	1264391688	<u>Offsets set to Zero</u>	435	0	0
1188	1264392876	<u>H1 reaches NLN</u>	600	0	0
	1264405772	<u>initial alignment</u>	7	0	0
0	1264407858	<u>ISC_LOCK = 110</u>	110	735	605
614	1264408472	<u>Offsets set to Zero</u>	435	0	0
1158	1264409630	<u>H1 reaches NLN</u>	600	0	0
0	1264440814	<u>ISC_LOCK = 110</u>	110	799	157
564	1264441378	<u>Offsets set to Zero</u>	435	0	0
1115	1264442493	<u>H1 reaches NLN</u>	600	0	0
	1264473865	<u>initial alignment</u>	7	0	0
0	1264475104	<u>ISC_LOCK = 110</u>	110	582	692
629	1264475733	<u>Offsets set to Zero</u>	435	0	0
1159	1264476892	<u>H1 reaches NLN</u>	600	0	0
0	1264529890	<u>ISC_LOCK = 110</u>	110	604	418
595	1264530485	<u>Offsets set to Zero</u>	435	0	0
1152	1264531637	<u>H1 reaches NLN</u>	600	0	0
0	1264541054	<u>ISC_LOCK = 110</u>	110	877	526
594	1264541648	<u>Offsets set to Zero</u>	435	0	0
1162	1264542810	<u>H1 reaches NLN</u>	600	0	0
0	1264595394	<u>ISC_LOCK = 110</u>	110	515	297
573	1264595967	<u>Offsets set to Zero</u>	435	0	0
1124	1264597091	<u>H1 reaches NLN</u>	600	0	0
	1264893476	<u>initial alignment</u>		0	0
0	1264894479	<u>ISC_LOCK = 110</u>	110	238	476
630	1264895109	<u>Offsets set to Zero</u>	435	0	0
1175	1264896284	<u>H1 reaches NLN</u>	600	0	0
0	1264906287	<u>ISC_LOCK = 110</u>	110	108	656
632	1264906919	<u>Offsets set to Zero</u>	435	0	0
1144	1264908063	<u>H1 reaches NLN</u>	600	0	0

<u>Average Pitch Offset</u>	588
-----------------------------	-----

<u>Average Yaw Offset</u>	478
---------------------------	-----