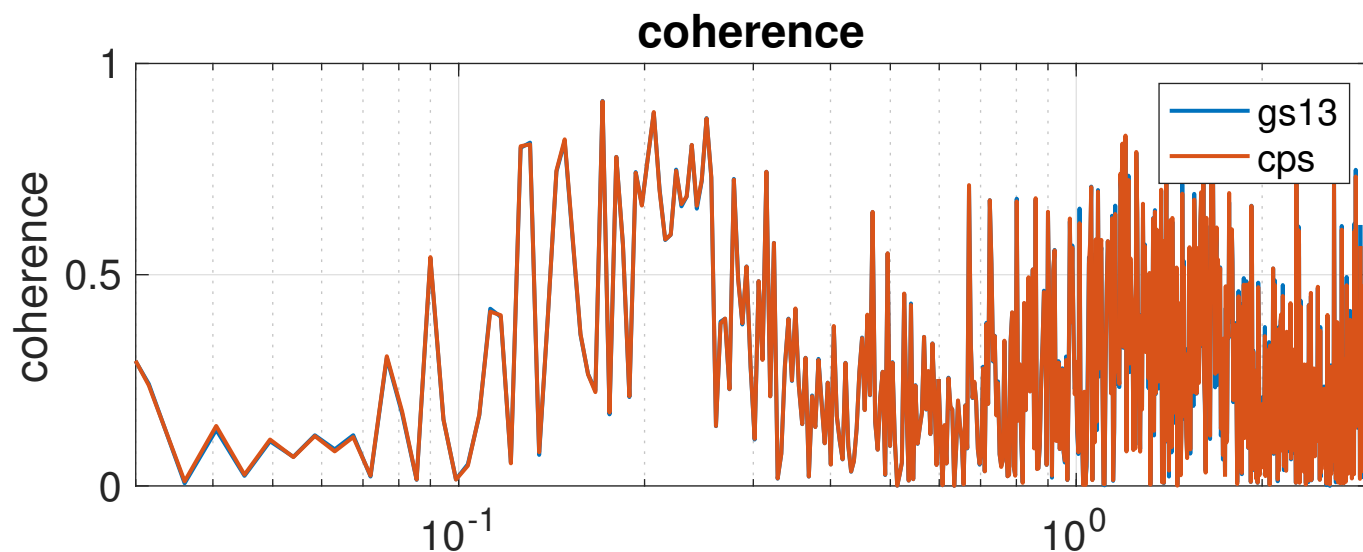
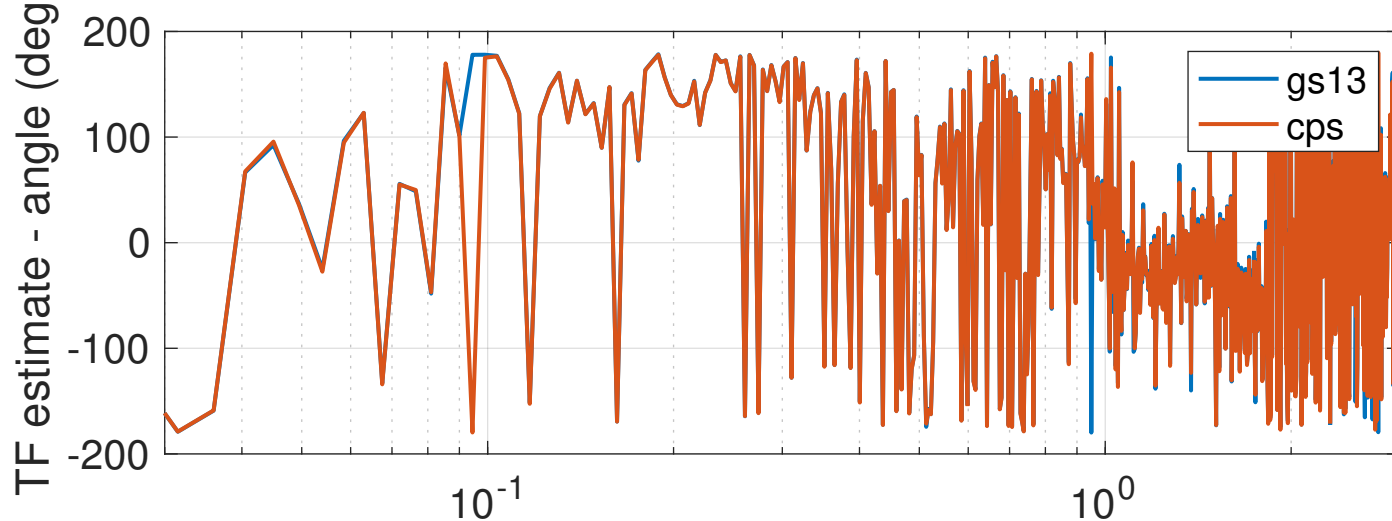
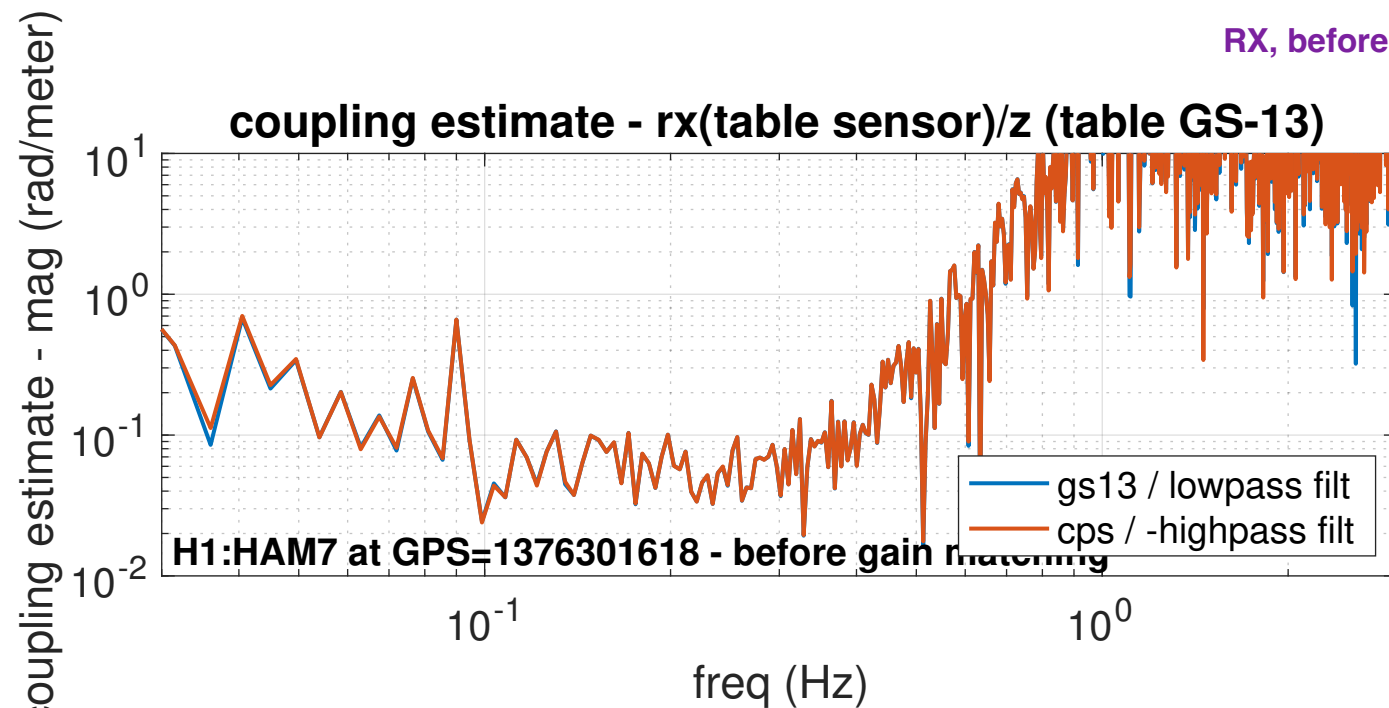
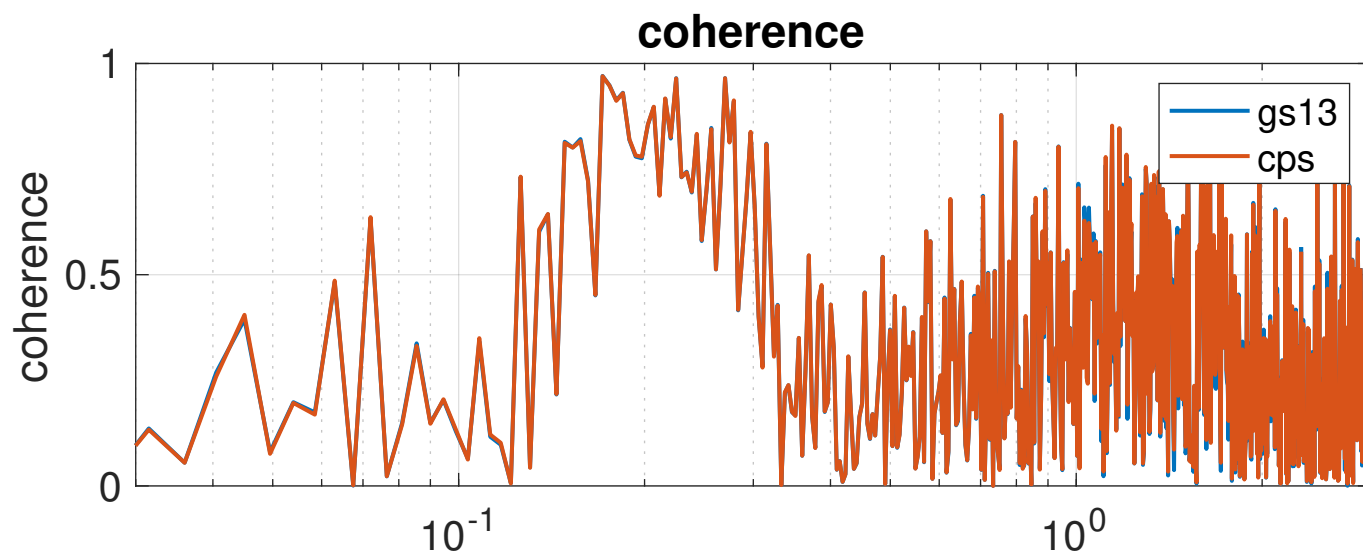
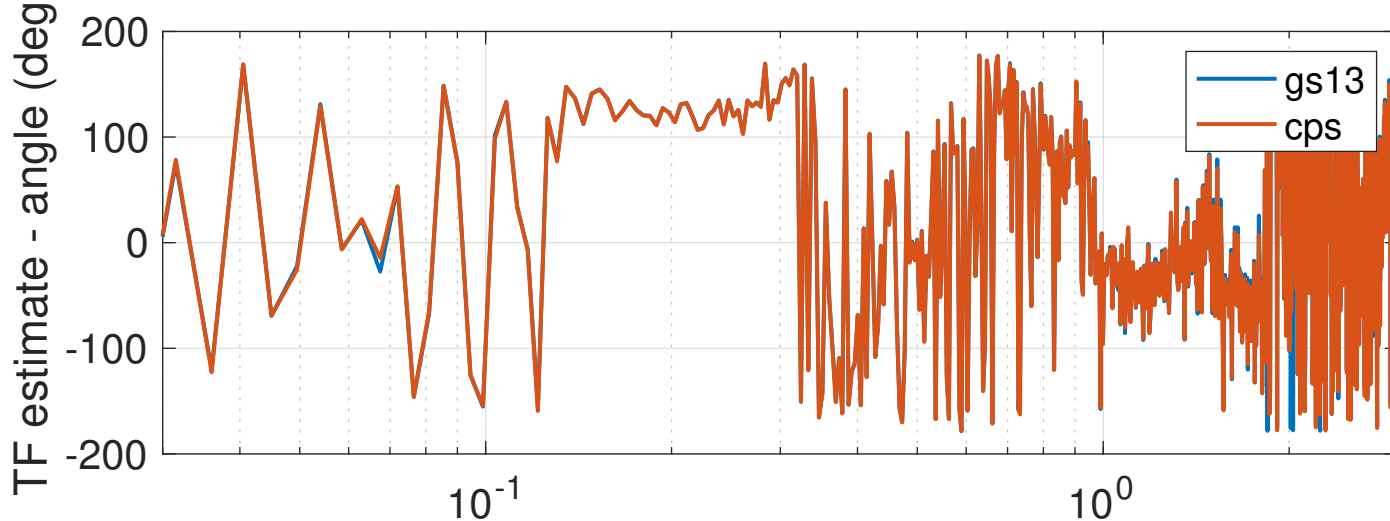
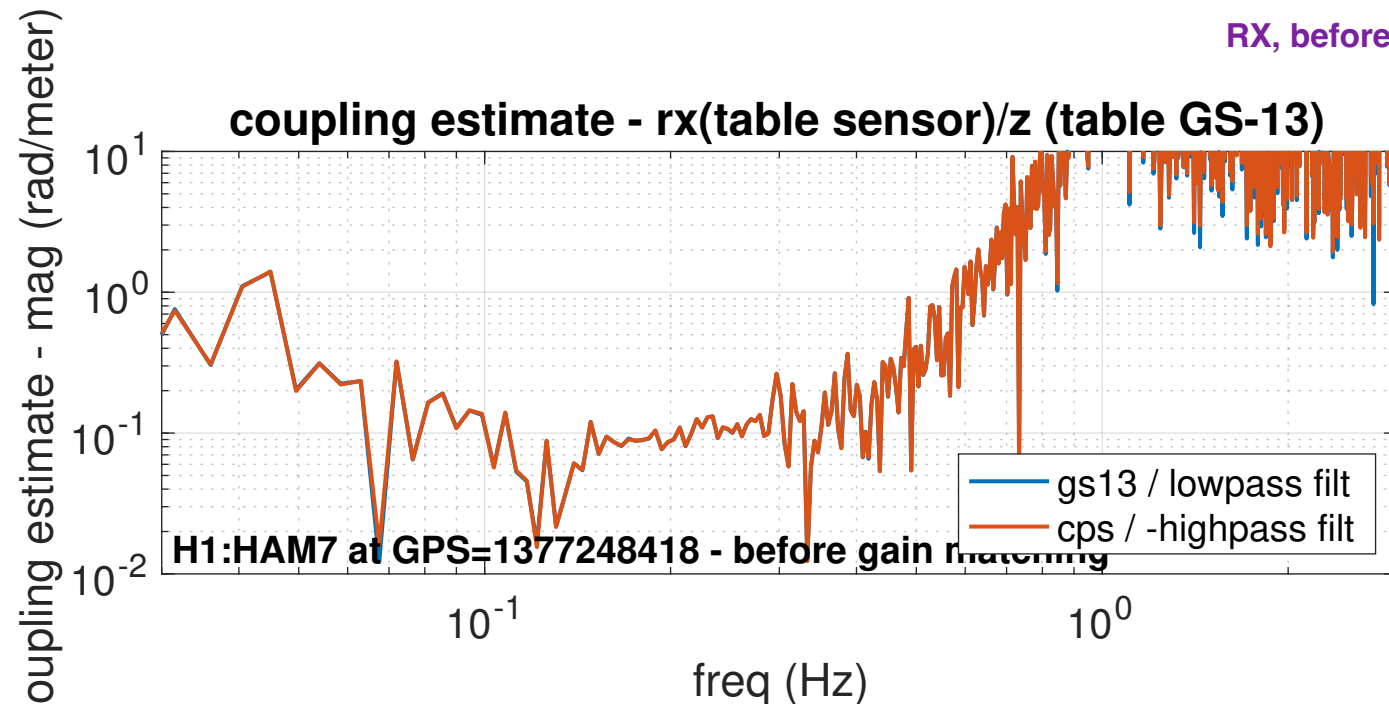


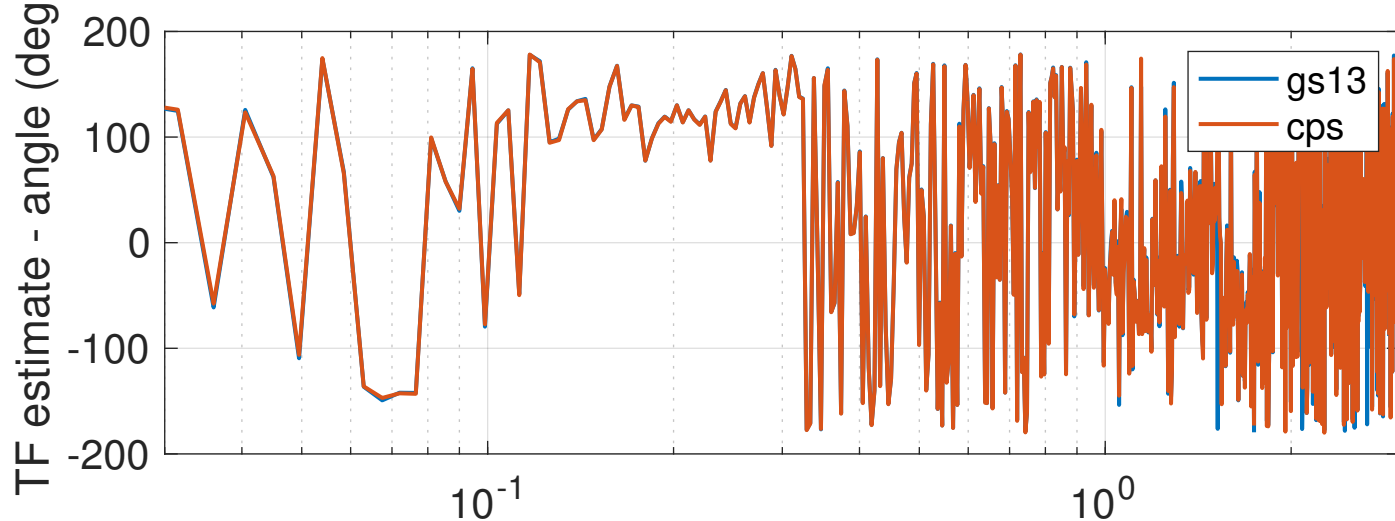
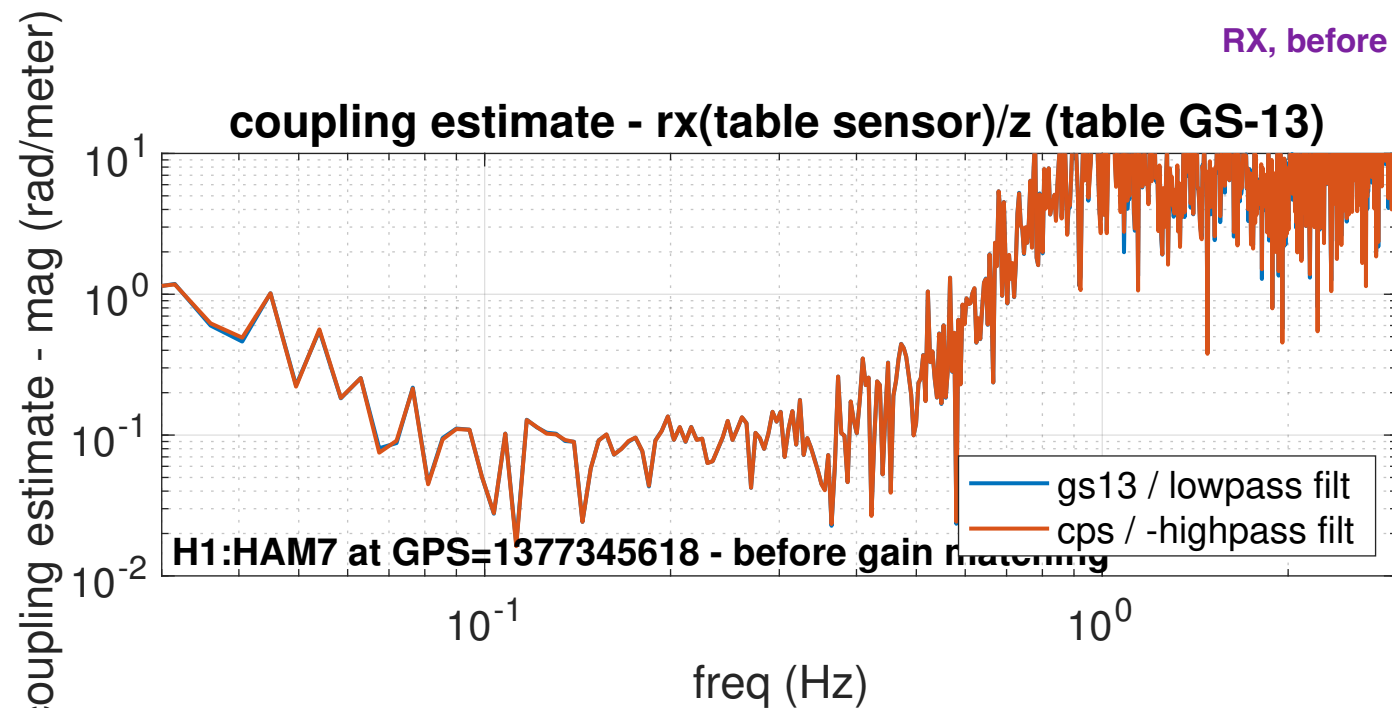
coupling estimate - rx(table sensor)/z (table GS-13)



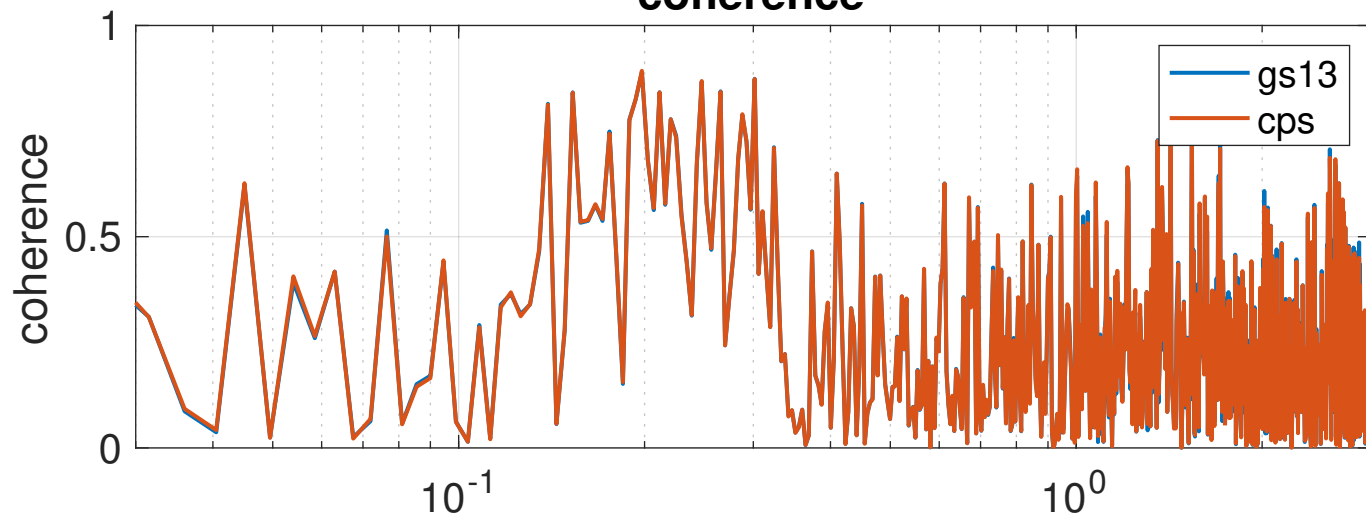
coupling estimate - rx(table sensor)/z (table GS-13)



coupling estimate - rx(table sensor)/z (table GS-13)

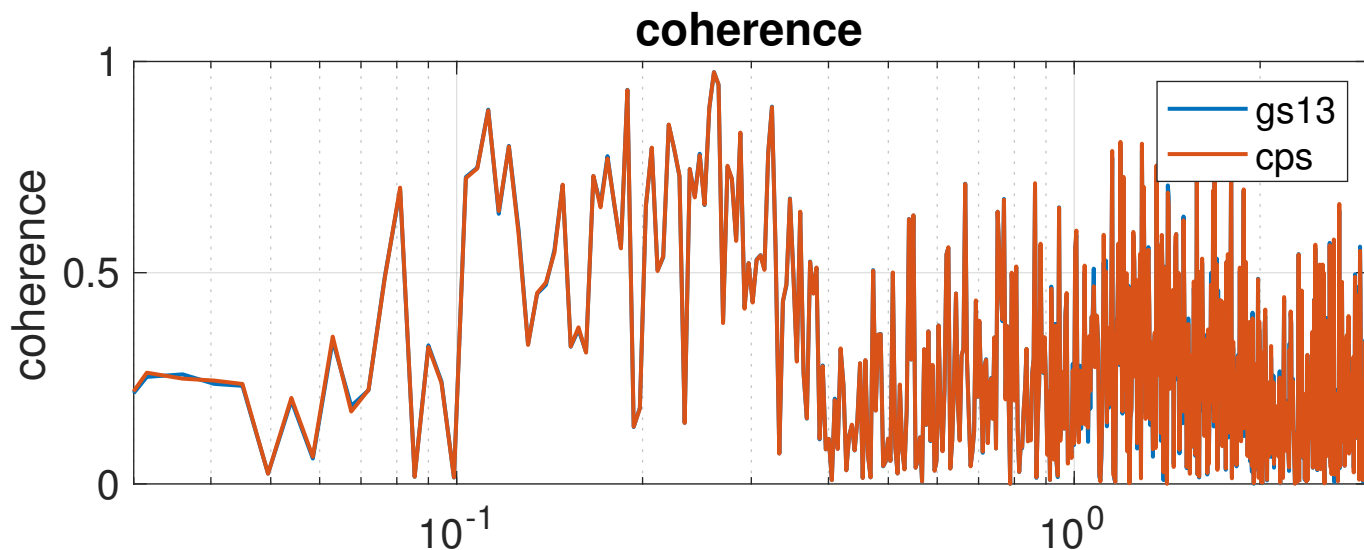
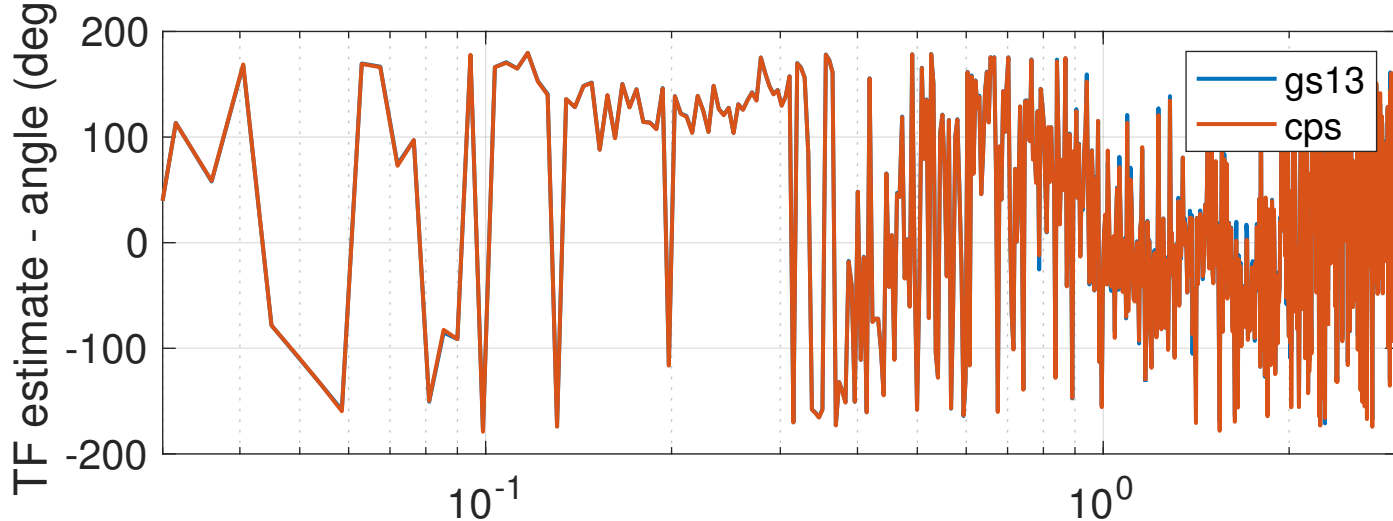
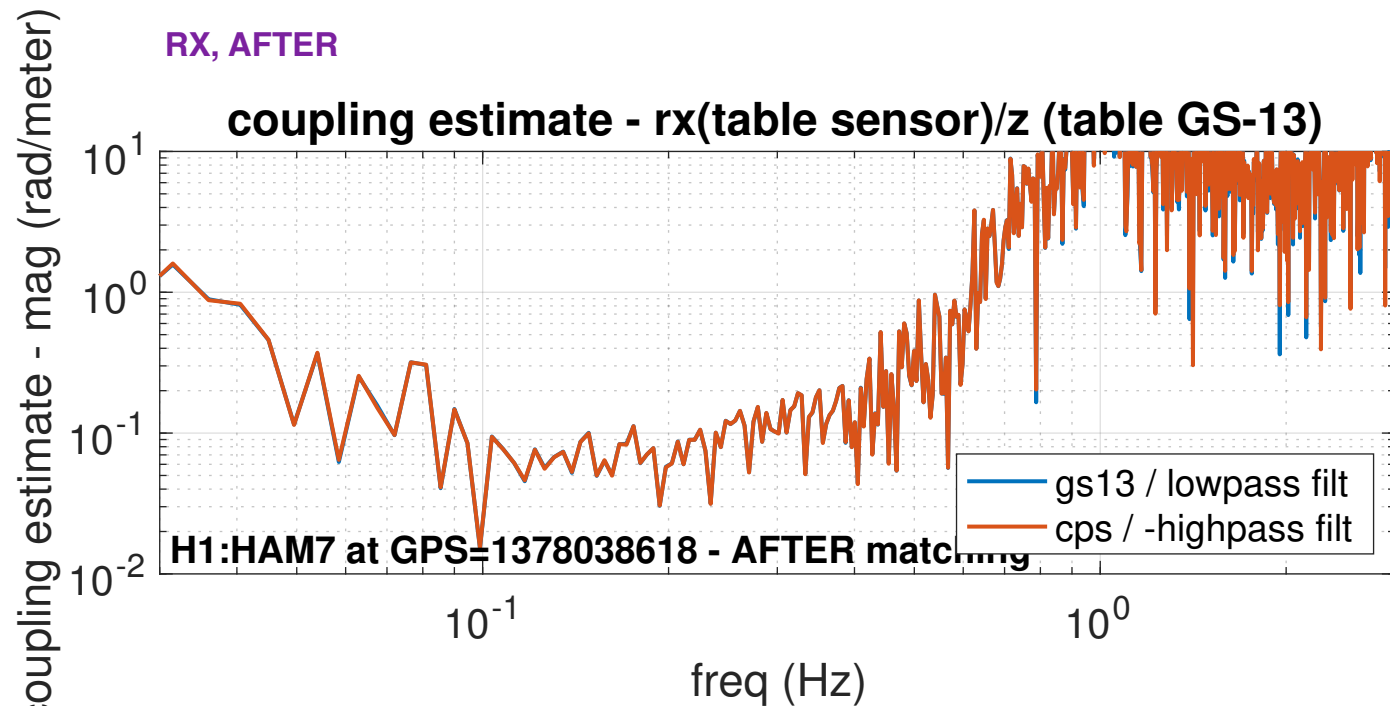


coherence



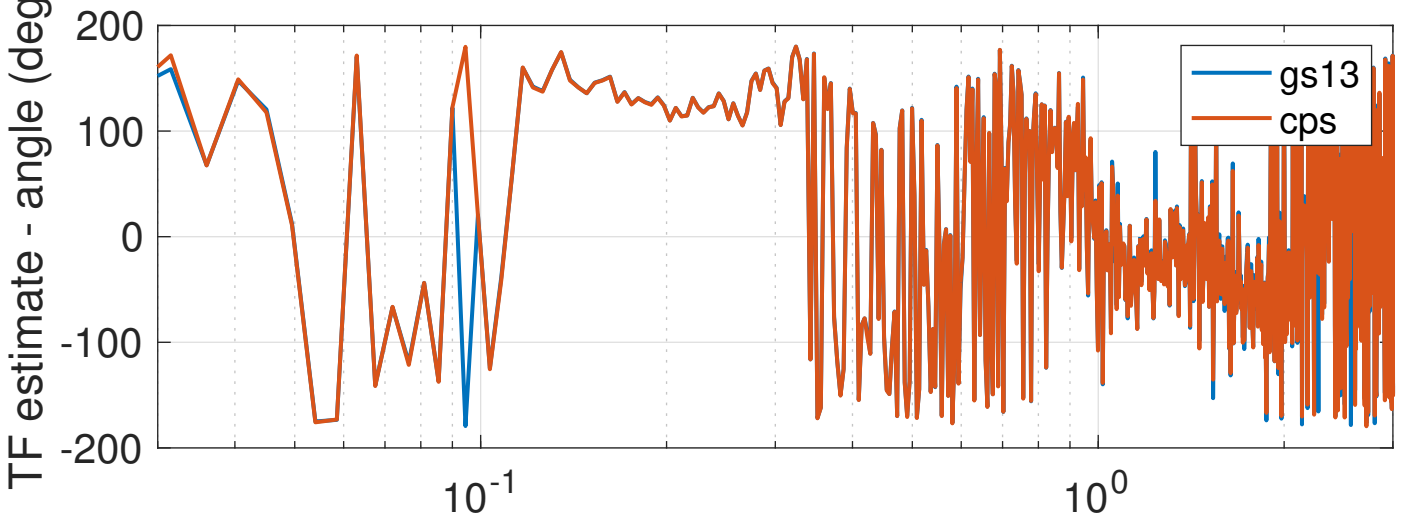
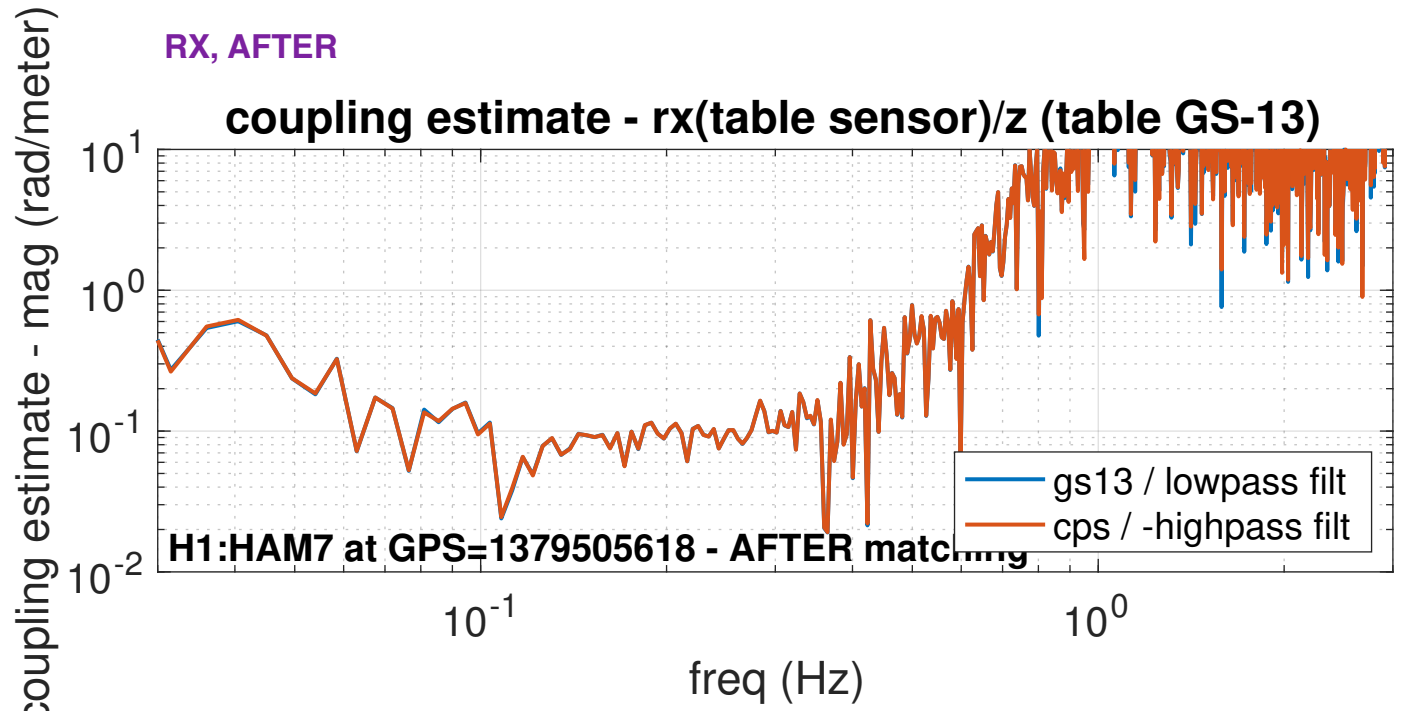
RX, AFTER

coupling estimate - rx(table sensor)/z (table GS-13)

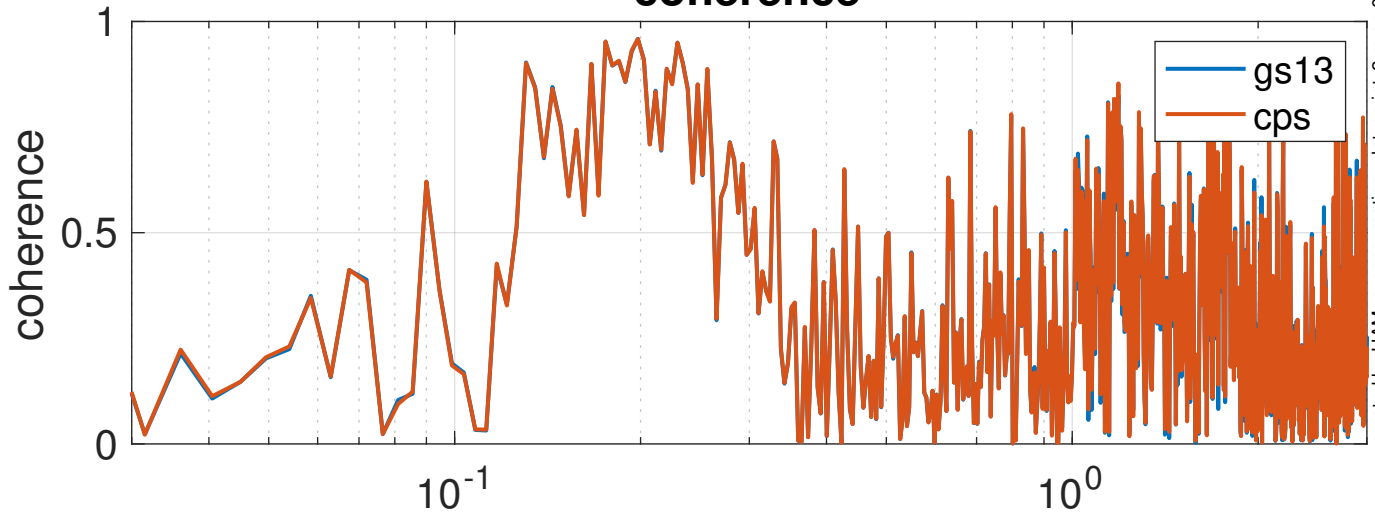


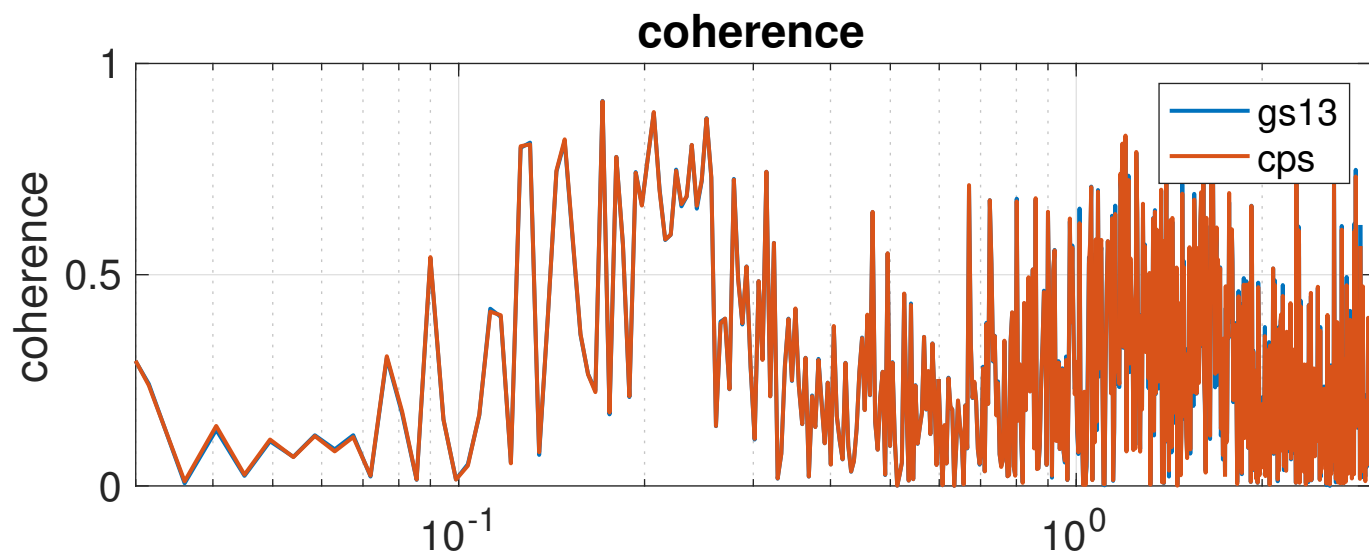
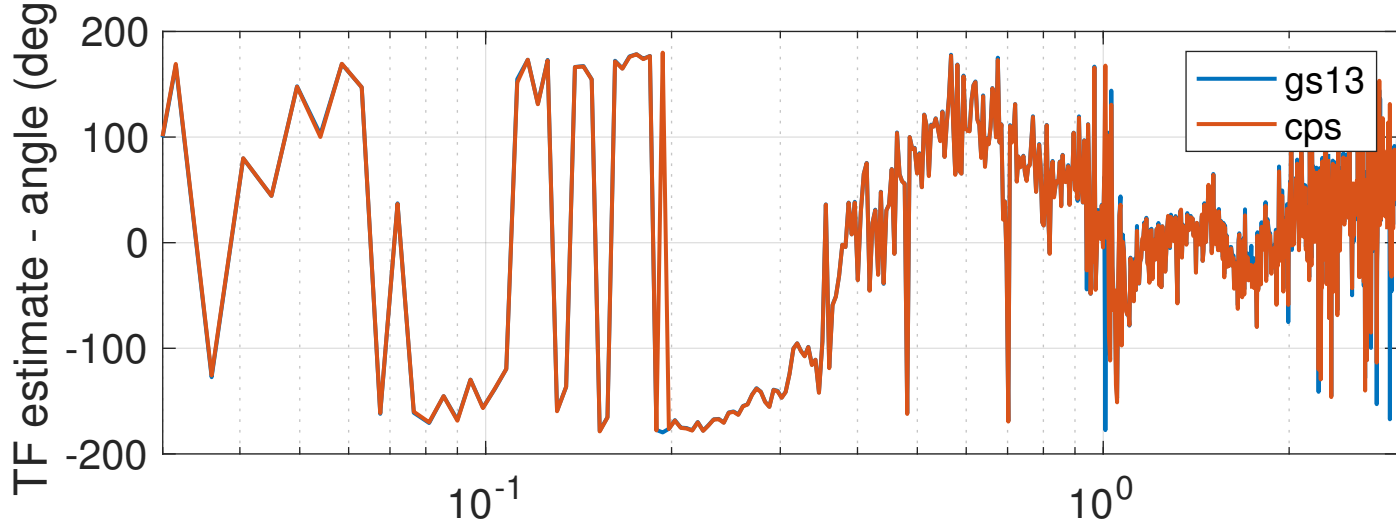
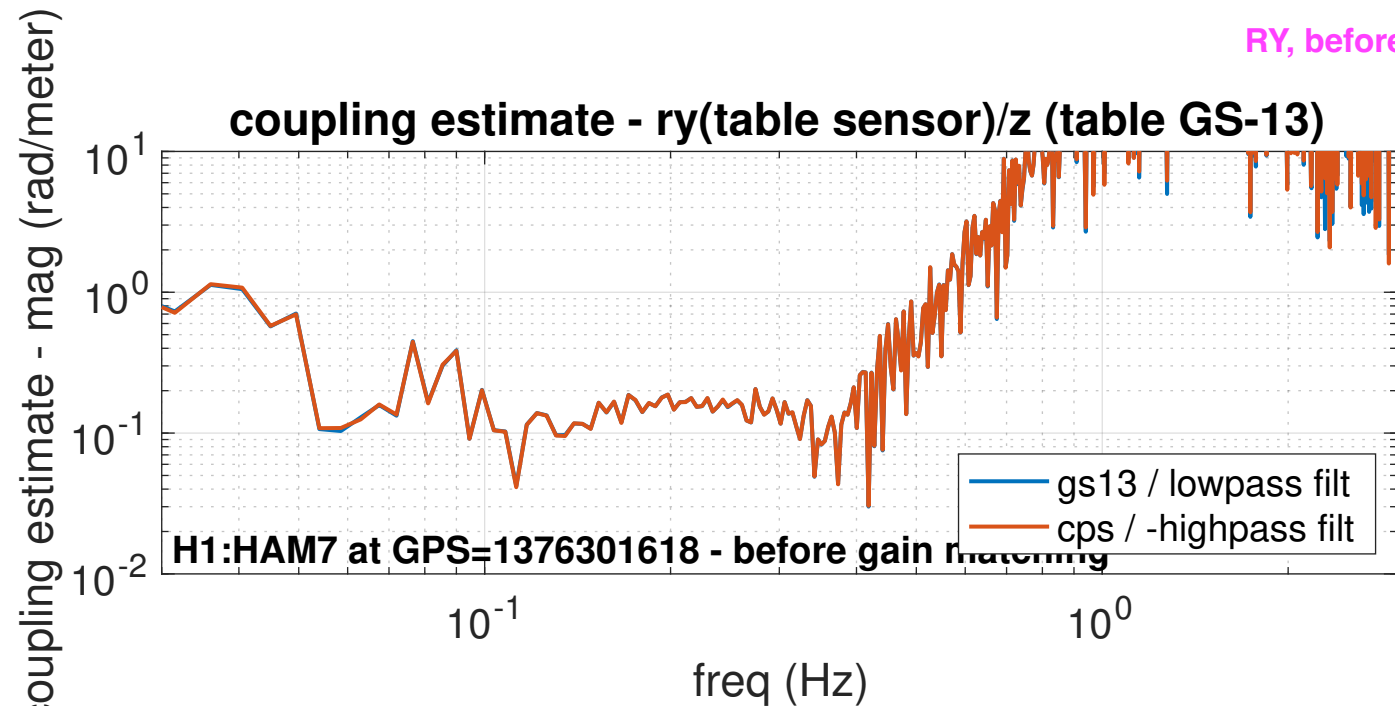
RX, AFTER

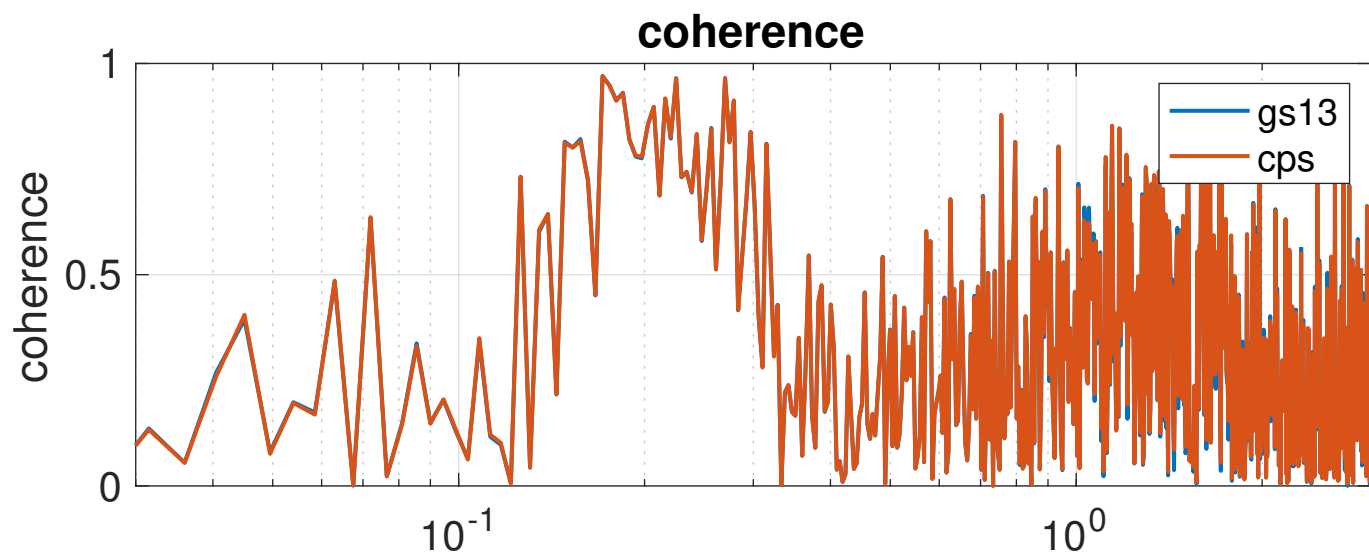
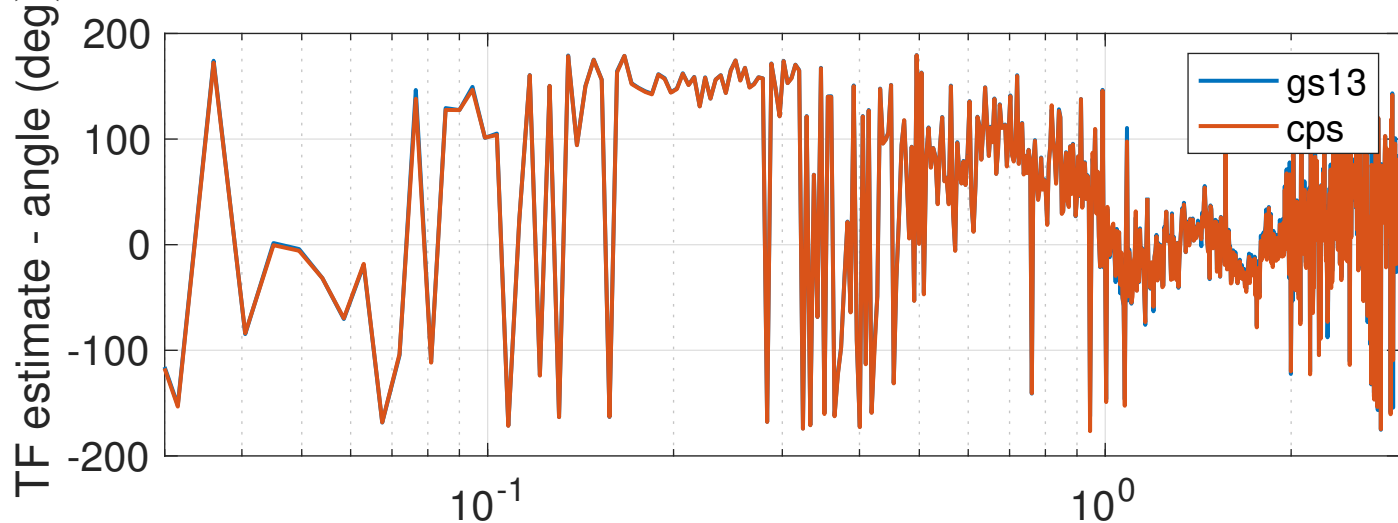
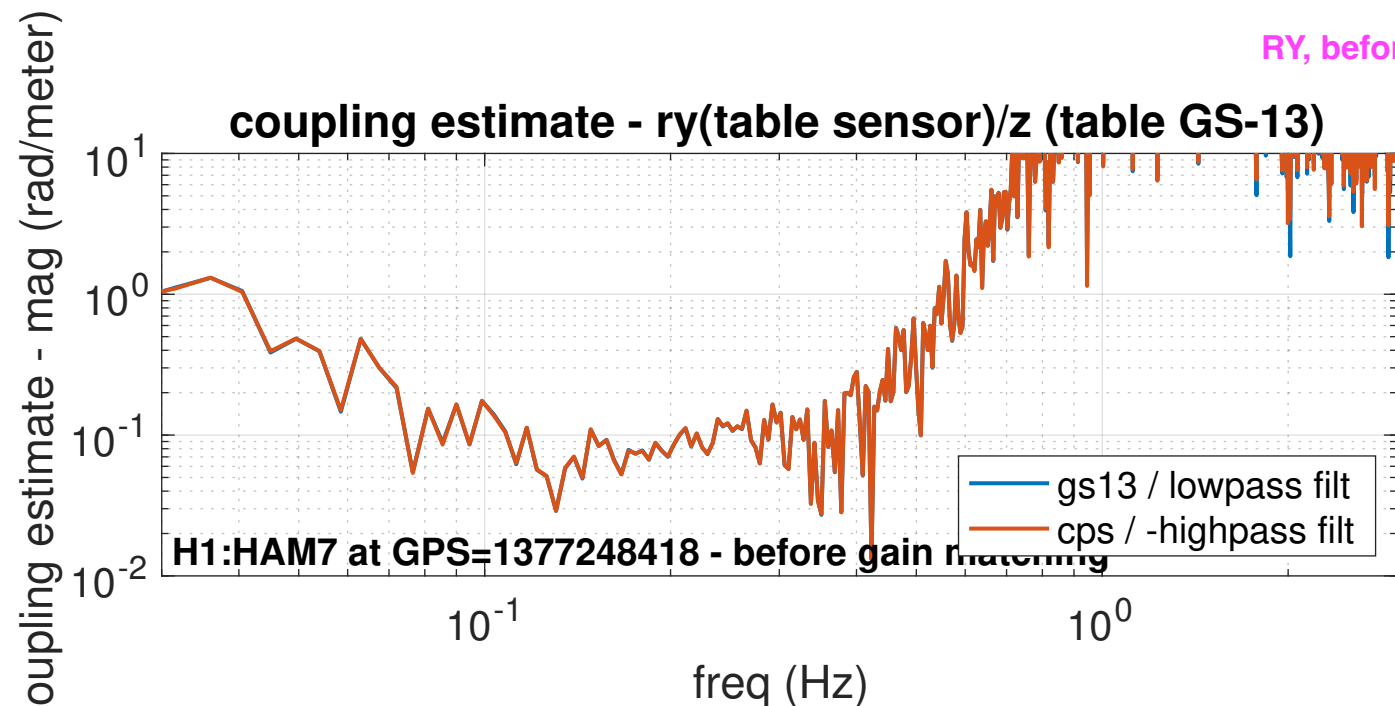
coupling estimate - rx(table sensor)/z (table GS-13)



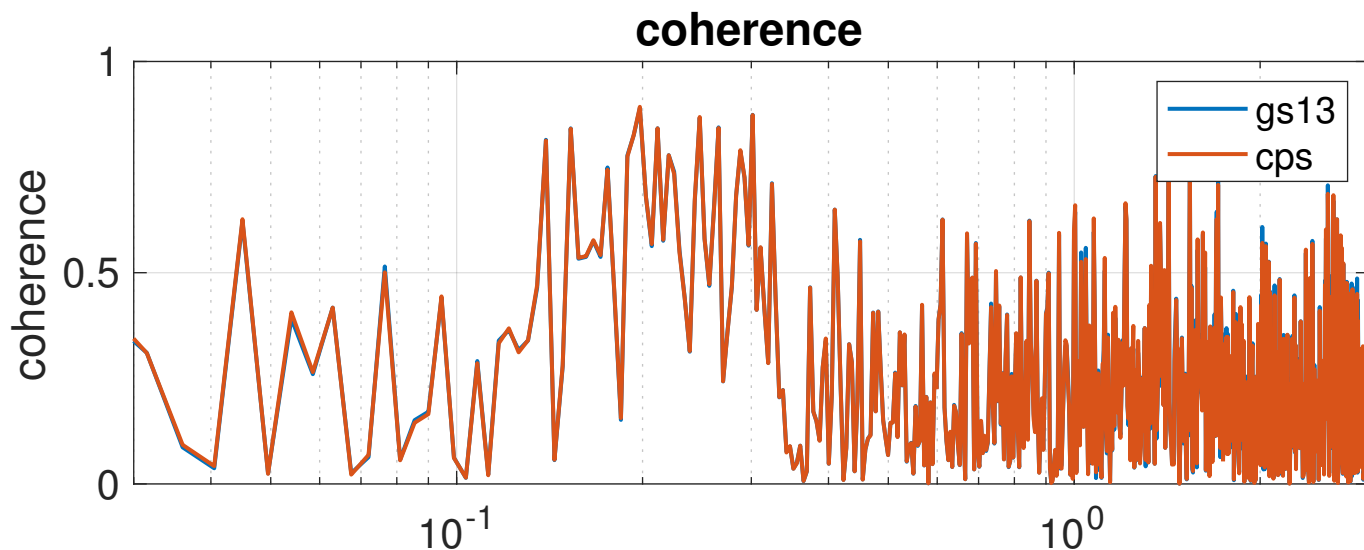
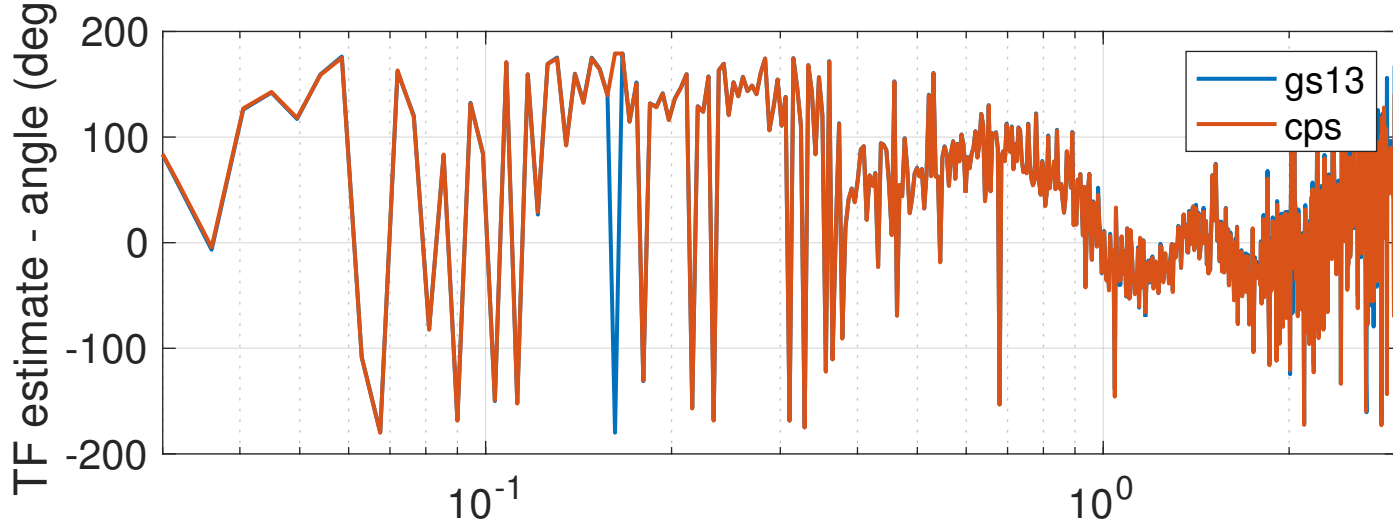
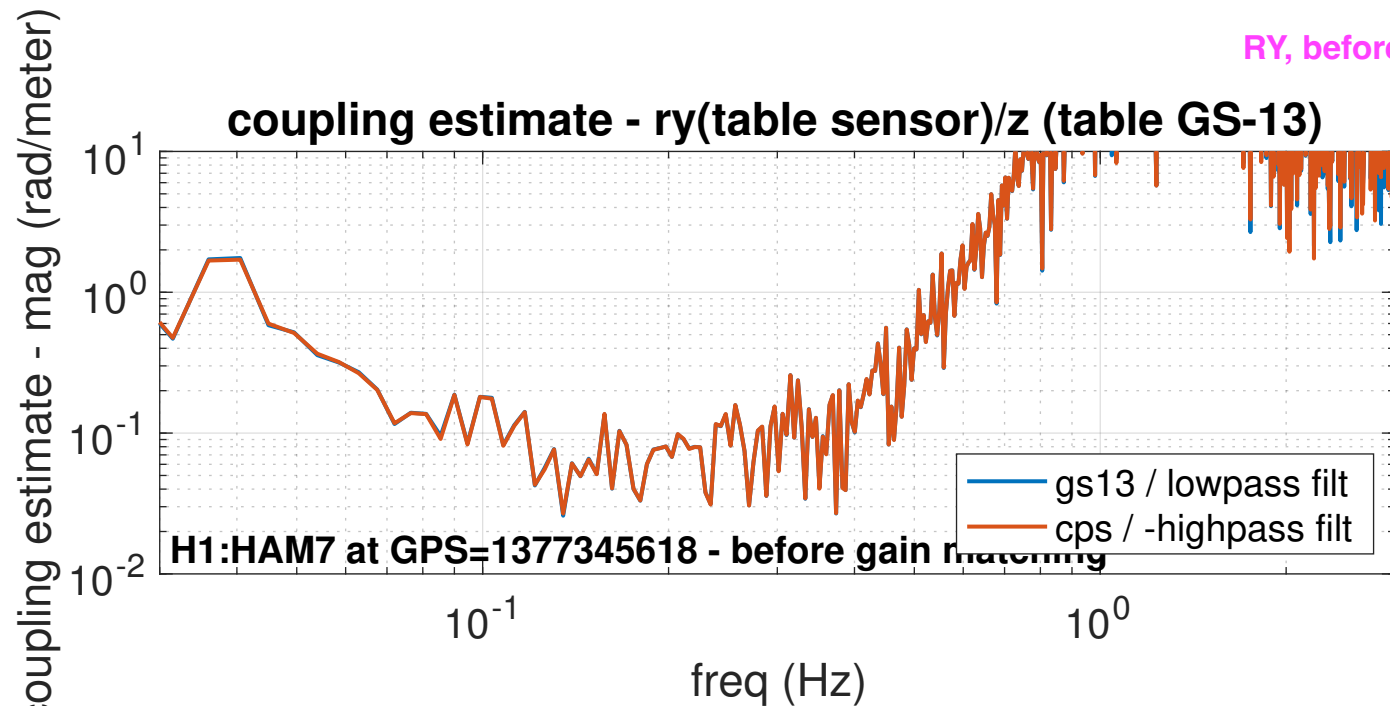
coherence





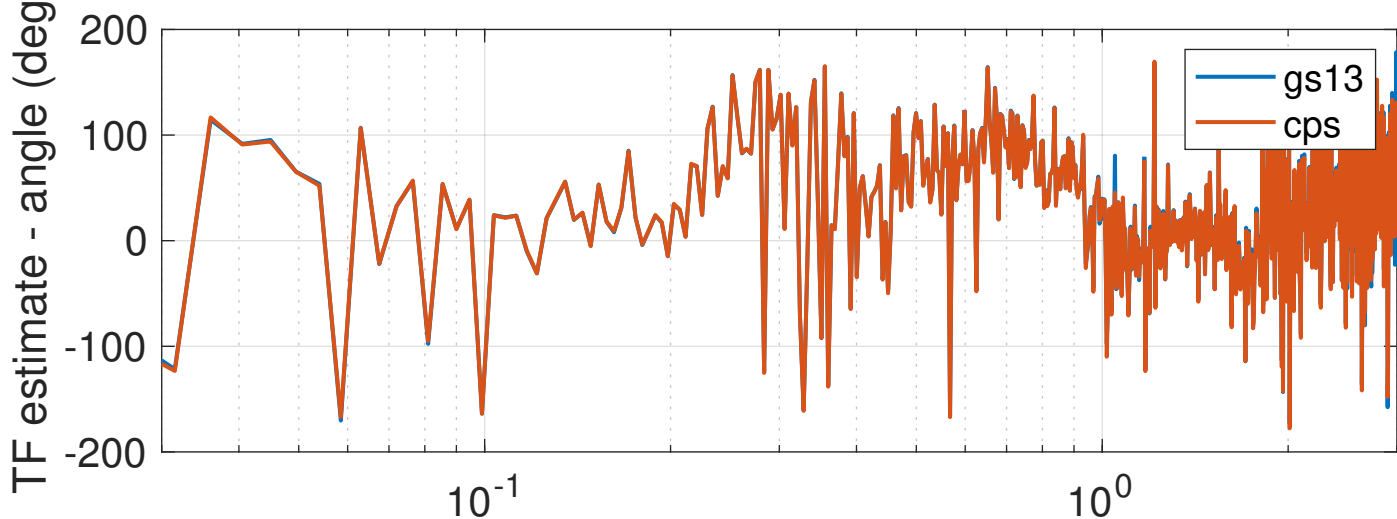
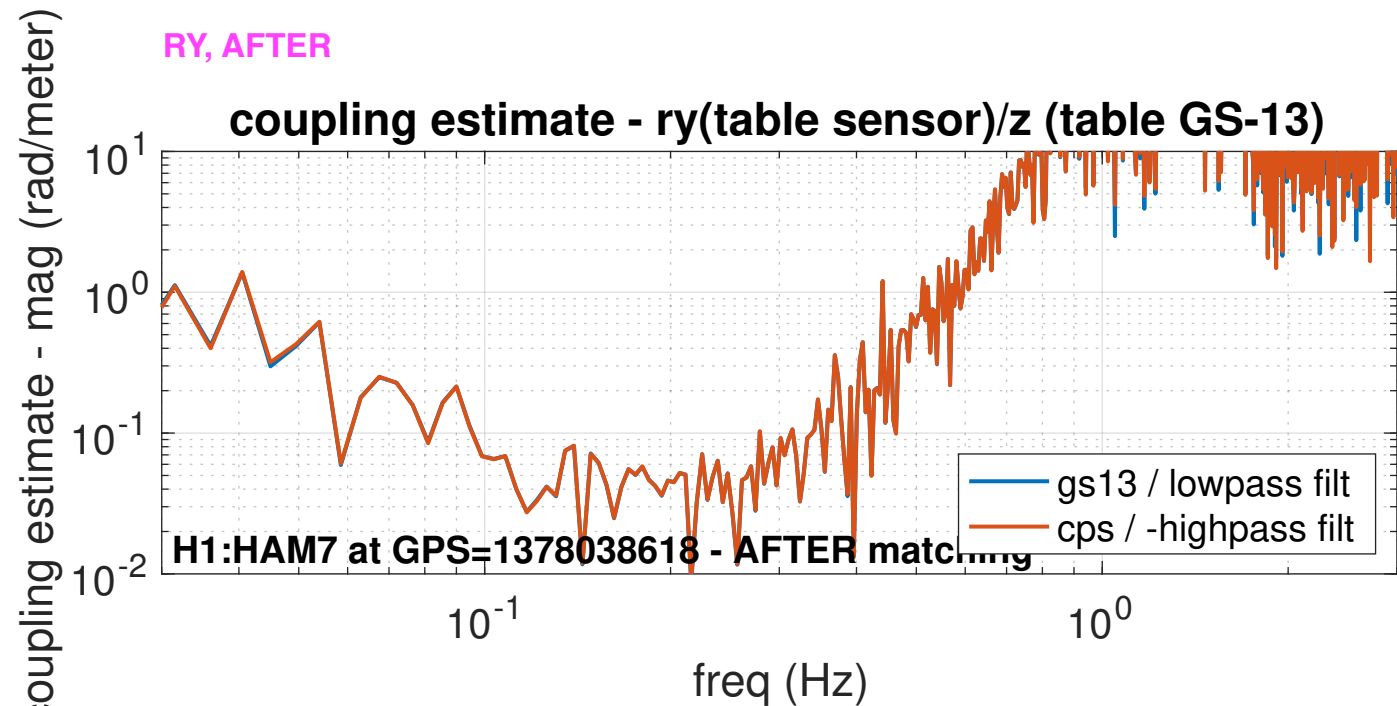


coupling estimate - ry(table sensor)/z (table GS-13)

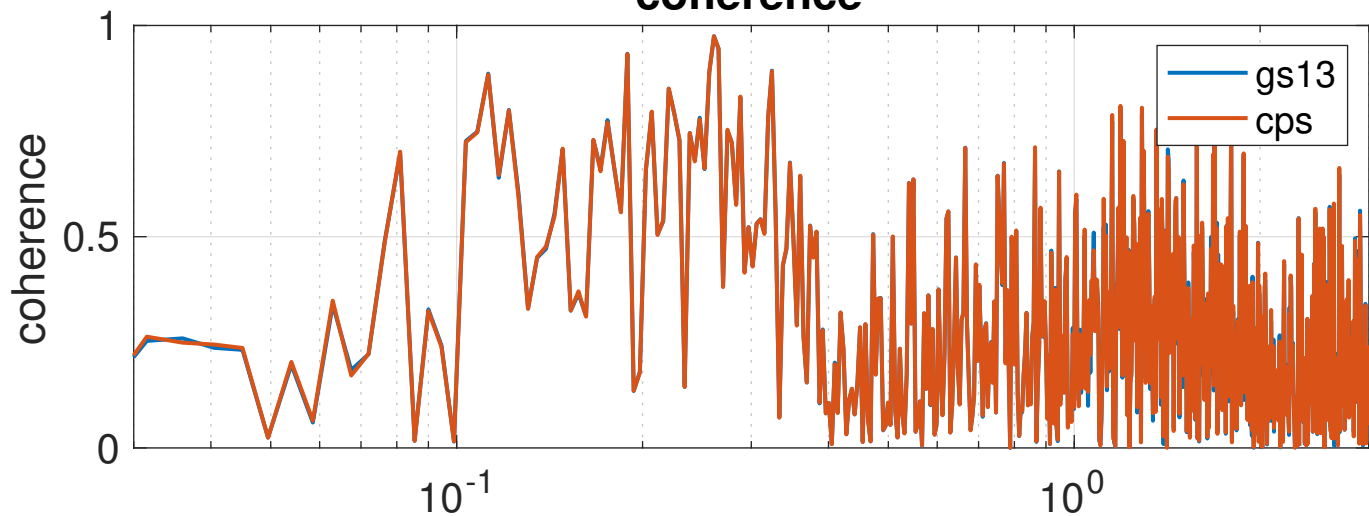


RY, AFTER

coupling estimate - ry(table sensor)/z (table GS-13)

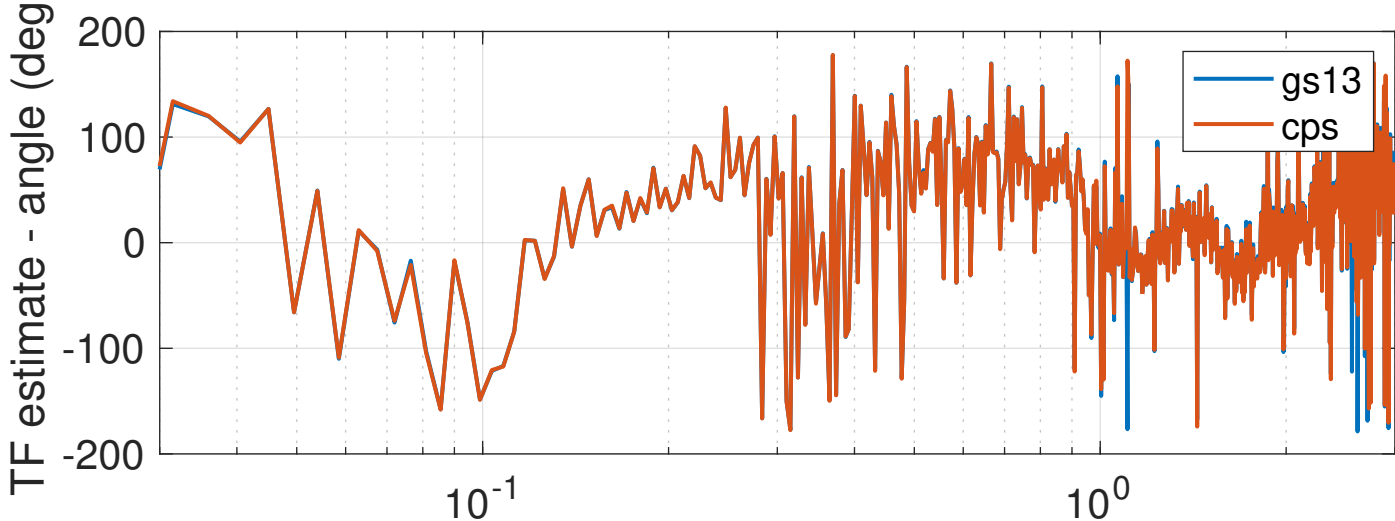
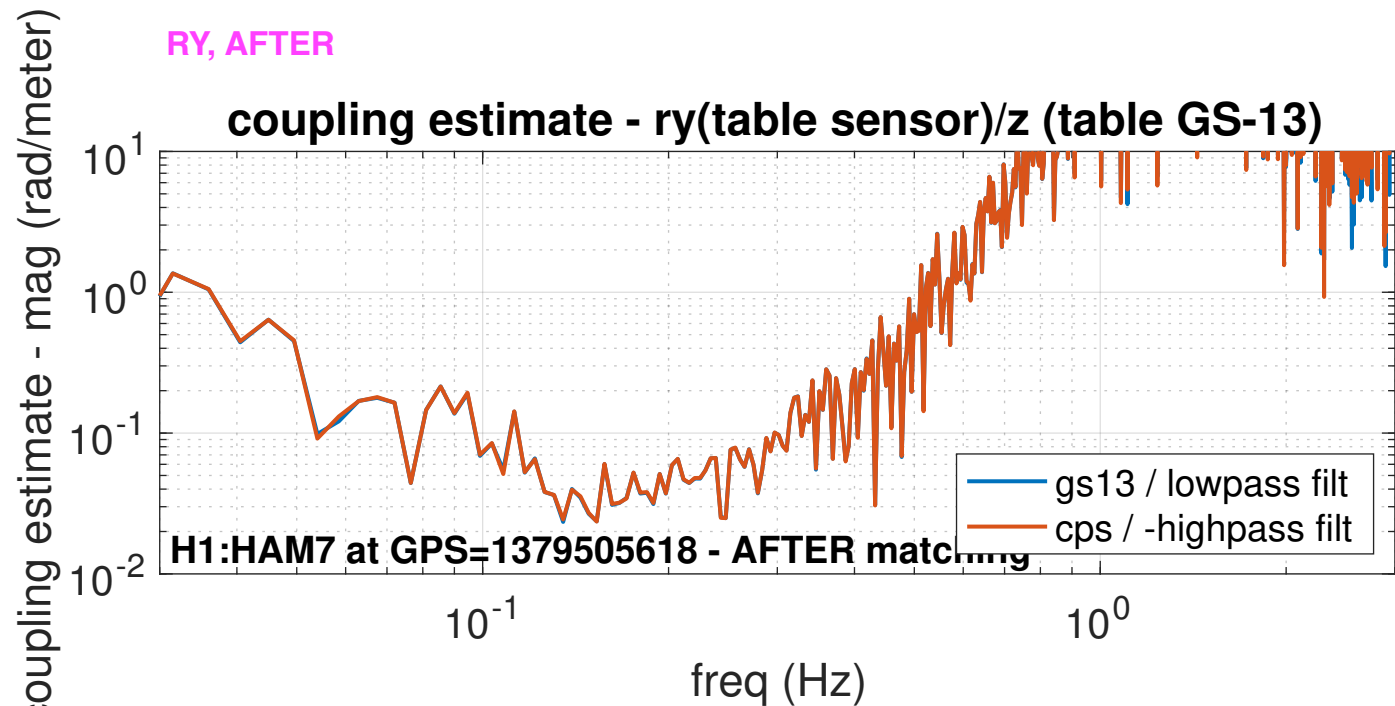


coherence



RY, AFTER

coupling estimate - ry(table sensor)/z (table GS-13)



coherence

